Outsourcing a Two-Level Service Process

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This paper studies outsourcing decisions for a two-level service process in which the first level serves as a gatekeeper for a second level of experts. The objective of the system operator (the client) is to minimize the sum of staffing costs, customer waiting costs, and mistreatment costs due to unsuccessful attempts by a gatekeeper to solve the customer's problem. The client may outsource all or part of the process to a vendor, and first-best contracts exist when the client outsources only gatekeepers or experts. When the client outsources the entire system as a two-level process, a client-optimal contract may not exist unless the exogenous system parameters satisfy a particular (and unlikely) coordination condition. In addition, optimal incentive-compatible contracts exist when the vendor's structure choice (one-level or two-level) can deviate from the client's preference. Finally, we numerically examine how vendor structure choice and labor cost advantages influence the client's optimal outsourcing option.

1. Introduction

When managing a service process a firm must specify both the workflow and how much capacity to allocate to each part of the process. When a process is outsourced the firm cedes control over these decisions. In this paper we investigate the implications of this loss of control. As this paper is the first in the literature to address outsourcing of workflow decisions in a service process we restrict our attention to a particular two-level customer service process. When a customer enters our process, he is screened by a gatekeeper (level one) who may then attempt to solve his problem. If the gatekeeper does not attempt to solve the problem, or if the attempt fails, the problem is solved by an expert (level two) who is more expensive for the firm. The customer request could be a call to a technical support center or to a health care triage service such as NHS Direct, a helpline operated by the National Health Service of England and Wales that employs hundreds of gatekeepers and expert providers (Taylor, 2010). In both the technical support and health care environments, the customer must directly participate in the entire service. Our model, however, also applies to systems in which the customer does not participate directly in all parts of the service, such as the processing of credit applications.

In this paper we will use the language of the health care setting to describe some components of the system, but the analysis will only apply to large systems such as call centers. We refer to the initial assessment by the gatekeeper as a *diagnosis*, the resolution of the customer's problem as a *treatment*, and a gatekeeper's unsuccessful attempt at resolution as a *mistreatment*. When a customer is mistreated he experiences both additional delay as well as the direct disutility of being mistreated. This poor service experience may lead to a loss in a customer's expected lifetime value to the firm, and we call this loss the *mistreatment cost*. Our model incorporates three decisions faced by managers of such two-level systems: staffing quantities for both levels and referral rules between them. We assume that managers are minimizing the sum of staffing, mistreatment, and customer waiting costs.

When a firm is outsourcing its process, we call the firm the *client* and we call the external service provider the *vendor*. We focus on four outsourcing options. First, the client can outsource the process as a one-level system in which the gatekeeper is eliminated. If she decides to break the system into two components, we consider three other outsourcing options for the client: outsourcing only the expert (system S_e), outsourcing only the gatekeeper (system S_g), or outsourcing both to the same vendor (system S_b). One can observe all four of these options in practice, e.g., Infosys, one of the largest outsourcing companies in India, offers the technical support services of gatekeepers and/or experts.¹ The client may also keep the process in-house as a one or two-level system.

In our model, the vendor maximizes his profits when choosing staffing levels and referral rates. Initially, we will assume that the client specifies the vendor's process design (e.g., one-level or twolevel). Then, we will incorporate vendor process choice into the model. In this paper, we consider the following questions:

¹http://www.infosys.com/global-sourcing/case-studies/networking-casestudy.asp

- 1 How does the client write effective contracts for each outsourcing option?
- 2 Which outsourcing option should the client choose, and how do the costs, such as the staffing, waiting, and mistreatment costs, affect her choice?
- **3** If the vendor is allowed to choose the process, how does vendor choice affect the client's outsourcing decision?
- 4 How does outsourcing affect the customer experience?

In general, this paper's goal is to examine how operational-level decisions interact with outsourcing decisions and contract design. We explicitly describe the flow of customers through this two-stage process, rather than treating the outsourced process as a black box that cannot be disaggregated.

2. Literature Review

This paper contributes to a relatively new stream of operations management research on services outsourcing and contracting. To date, this literature has focused on processes with a single interaction between the customer and agent (a one-level system). This stream includes Ren and Zhou (2008), who study contracts that coordinate the vendor's staffing and service quality decisions. Ren and Zhang (2009) examine coordinating contracts under unknown and correlated capacity and quality costs, while Hasija et al. (2008) examine screening contracts that may be used by a client when the vendor's service rate is uncertain. Allon and Federgruen (2005) examine contracts for common outsourced services under price and time competition. Akşin et al. (2008) assume that arrival rates are uncertain and study contracts that allow the client to outsource the base customer demand or to outsource the peak demand. The model in our paper incorporates two, rather than one, level of agents.

As in our model, Lu et al. (2009) allow customers or products to visit multiple workers, for their system allows for rework. They examine how wage and piece-rate compensation packages affect workers' efforts to reduce the need for rework. They do not consider outsourcing sub-components of the system, as we do here.

The two-level system described here is related to Shumsky and Pinker (2003) and Hasija et al. (2005). Shumsky and Pinker (2003) describe a similar model of gatekeepers and experts, and they derive the optimal referral rate in a two-level system with deterministic service times and

deterministic customer inter-arrival times. Modeling the management of gatekeepers as a principalagent problem, Shumsky and Pinker find that incentives with both pay-per-service and pay-persolve components can induce the gatekeeper to choose the system-optimal referral rate. Hasija et al. (2005) extend this deterministic model to a stochastic setting. The model in this paper generalizes the models in these previous papers in a variety of ways. The most significant difference, however, is that this paper focuses on the outsourcing and contracting issues while Shumsky and Pinker (2003) focus only on the referral decision and Hasija et al. (2005) only consider a centralized system.

There is also a stream of economics literature about the role of gatekeepers, particularly in health care. Marinoso and Jelovac (2003) and Malcomson (2004) describe optimal contracts for gatekeepers, given that gatekeepers choose a level of diagnosis effort, and then may choose to treat or refer patients. Brekke et al. (2007) focuses on the gatekeeper's role in allocating patients to the most appropriate secondary care provider (what we call experts). These papers do not address our topic: the financial and operational implications of aggregating or disaggregating and outsourcing the gatekeepers and experts.

3. Model

Our model for the two-level structure (Figure 1) follows Shumsky and Pinker (2003). The gatekeeper spends time diagnosing every customer's request and then decides whether to attempt treatment. The complexity of a customer's problem is represented by a real number $x \in [0, 1]$, which is defined as the fractile of complexity and therefore is uniformly distributed. Because requests are ranked by complexity a customer request with $x < x_0$ is more likely to be solved by the gatekeeper than every request with $x \ge x_0$. The gatekeepers' skill levels are described by a treatment function f(x), the probability that a request at the x fractile of treatment complexity for a gatekeeper can be successfully treated by that gatekeeper. The function f(x) is strictly decreasing, continuous and differentiable. From the definition, f(x) is between 0 and 1, and f'(x) < 0 implies that if the service is more complex, the probability that a gatekeeper can successfully treat the problem is smaller. To simplify the exposition we initially assume that the gatekeeper can accurately diagnose the complexity x for each request. We relax this assumption in Section 7.

The function $F(k) = \int_0^k f(x) dx$ is the expected fraction of requests that are successfully treated by a gatekeeper who chooses to treat all customer requests with complexity up to k. We call k the *treatment threshold*, and it is a decision variable in the system, along with the staffing levels. From the definition, the function F(k) lies between 0 and k. For now we assume that any customer not



Figure 1: The two-level service process

successfully treated by a gatekeeper is then referred to, and successfully treated by, an expert. In Section 7.2 we will extend the model so that experts may also mistreat customers. We also assume that F(1) < 1, otherwise, we do not need experts at all. The workflow is shown in Figure 1. The figure shows that the mean total arrival rate to the experts is $\lambda_e(k) = (1 - F(k))\lambda$.

The gatekeeper's (expert's) mean treatment times $t_g(x)$ ($t_e(x)$) are functions of the problem complexity x. Treatment time should rise as complexity rises, so we assume that t_e and t_g are increasing in x, as well as continuous and differentiable. Given that the gatekeeper chooses treatment threshold k, $T_g(k) = \int_0^k t_g(x) dx$ is the expected gatekeeper treatment time averaged over all customers, including those not treated by gatekeepers. The quantity $T_g(k)/k$ is the expected treatment time of a customer, given that the customer is treated by a gatekeeper. Note that $\partial T_g(k)/\partial k = t_g(k) > 0$ and $\partial^2 T_g(k)/\partial k^2 = t'_g(k) > 0$. Let μ_d be the gatekeeper's service rate for a diagnosis, and therefore the service rate for a gatekeeper using treatment threshold k is $\mu_g(k) = [1/\mu_d + T_g(k)]^{-1}$.

If the gatekeeper chooses treatment threshold k, the expected expert treatment time averaged over all customers is $T_e(k) = \int_0^k t_e(x)(1-f(x))dx + \int_k^1 t_e(x)dx$. The quantity $T_e(k)/(1-F(k))$ is the expected treatment time, given treatment by an expert. The derivatives $\partial T_e(k)/\partial k = -t_e(k)f(k)$ and $\partial^2 T_e(k)/\partial k^2 = -V(k)$, where $V(k) = t'_e(k)f(k) + t_e(k)f'(k)$. The expert's service rate, given gatekeeper threshold k, is $\mu_e(k) = 1/[T_e(k)/(1-F(k))]$.

The client incurs costs for staffing, customer waiting and mistreatment. The gatekeeper and expert wage rates are C_g and C_e respectively, the customer waiting cost per unit time is C_w , and the cost per mistreatment by a gatekeeper is C_m . Note that wage rates C_g and C_e may differ between the client and the vendor. We will not add notation to distinguish between client and vendor wages, but the appropriate interpretation should be obvious from the context. For example, when outsourcing only gatekeepers, C_g refers to the vendor's gatekeeper wage rate while C_e refers to the client's expert wage rate.

We adopt the following notation when describing the client's costs and the vendor's profits: $\pi_c^j(\mathbf{y}) =$ the client's cost when the service option j is selected, given that the client makes decision \mathbf{y} (a vector), and similarly $\pi_v^j(\mathbf{y}) =$ the vendor's profits when the service option j is selected. Four outsourcing options are considered in our paper: $j \in \{e, g, b, 1\}$, in which e = system S_e with experts outsourced, g = system S_g with gatekeepers outsourced, b = system S_b with both outsourced, and 1 = the one-level structure, in which the customers are treated directly by an expert without being diagnosed by a gatekeeper. For example, $\pi_v^g(k, n_g)$ represents the vendor's profit function (subscript v) in system S_g (superscript g), when the vendor sets the treatment threshold to k and hires n_g gatekeepers. Finally, when the system is centralized with no outsourcing, the client's cost function has no superscript, e.g., $\pi_c(k, n_g, n_e)$

4. Centralized System

We first analyze the two-level system when both subsystems are performed in-house by the client. The client's objective is to minimize expected cost by choosing the numbers of gatekeepers, n_g , and experts, n_e , as well as the treatment threshold for gatekeepers, k. The client pays for the gatekeepers, experts, and two indirect costs, the waiting and mistreatment costs. We use W_g and W_e to represent the expected waiting times in the gatekeeper and expert queues, respectively, and these are functions of the decision variables. The client's expected cost is,

$$\pi_c(k, n_g, n_e) = [C_g n_g + C_e n_e] + C_w [W_g \lambda + W_e \lambda_e(k)] + C_m (k - F(k))\lambda.$$
(1)

From (1) we can also see that for a given k, the mistreatment costs are completely determined, as are the workloads at each level of the system. Therefore, for a fixed k the gatekeeper and expert subsystems can be decoupled.

To derive expressions for the waiting time at each level that will enable us to determine optimal staffing levels, we make a few simplifying approximations. Such approximations are necessary because total gatekeeper service times are the sums of diagnosis and treatment times, and the distribution of treatment time varies according to problem complexity. Therefore, a detailed model of the system would require a continuous mixture of exponential distributions for gatekeeper service times, as well as a model of the non-Poisson arrival process from gatekeepers to experts.

There are, however, no existing analytical expressions for waiting times in such systems. Therefore, we first assume that the customer arrival process to the gatekeepers is Poisson. Second we approximate the service-time distributions at both the gatekeeper and expert levels as exponential random variables with rates $\mu_g(k)$ and $\mu_e(k)$, respectively. Our final approximation is that the arrival process to the expert queue is Poisson as well.

The above approximations imply that for a fixed threshold k the two subsystems (gatekeeper and expert) can be analyzed independently as M/M/N queueing systems. In particular, if we assume we are operating in one of the asymptotic regimes described in Borst et al. (2004), we can use square root rules to determine the optimal staffing. In the remainder of the paper, analytical results apply to any of the regimes described in Borst et al. For our tests of approximation accuracy and our numerical experiments, we will assume that we are in the QED regime of Halfin and Whitt (1981), who provide closed-form expressions for expected waits. In Appendix A we use simulation to show that the QED approximations are accurate for large systems, as measured by errors in the estimated total cost of the system. Systems with loads greater than 50 at both the gatekeeper and expert levels had total cost approximation errors that averaged 0.5%, with a maximum error across all experiments of 4.3%.

To apply the square root staffing rule we need both subsystems to operate in the asymptotic regime. For the gatekeeper subsystem, we assume that the arrival rate λ is large enough so that this is true. For the arrivals to the expert subsystem, for any k, $\lim_{\lambda\to\infty} \lambda_e(k)/\lambda = \lim_{\lambda\to\infty} \lambda(1 - F(k))/\lambda = \lim_{\lambda\to\infty} (1 - F(k)) \ge 1 - F(1) > 0$, where the last two steps follow from $F(k) \le F(1) < 1$. Therefore, as $\lambda \to \infty$, $\lambda_e(k) \to \infty$ no slower than λ , for any k, and we can assume that the expert subsystem has a sufficiently large arrival rate as well.

To simplify notation, for the rest of the paper we suppress the dependence of $\mu_g(k)$, $t_g(k)$, $T_g(k)$, $\mu_e(k)$, $t_e(k)$, $T_e(k)$, and $\lambda_e(k)$ on k. It will also be useful to define $\rho_g = \lambda/\mu_g$ and $\rho_e = \lambda_e/\mu_e$, and again we will usually not express the dependence of these system loads on k.

4.1 Square Root Staffing Rule

Following Borst et al. (2004), consider a single-queue system with an arrival rate of λ , a service rate of μ , and N servers. While we assume that the system is in the QED regime, Borst et al. (2004) show that variants of the following square root staffing rules apply to other regimes as well. The optimal staffing level is $N = \rho + \beta \sqrt{\rho}$, in which $\beta > 0$ can be seen as the standardized excess capacity to manage system variability. We can always find a β that meets any desired service requirement. In this paper, we quantify the service requirement by the waiting time, and the goal is to minimize the expected total cost

$$C_n N + C_w \lambda W,\tag{2}$$

where C_n is the unit cost per worker, C_w is the waiting cost per unit time, and W is the mean waiting time in the system. For an M/M/N queue in the QED regime, the expected waiting time W is a function of β , λ , and μ (Halfin and Whitt 1981):

$$W = \frac{\alpha(\beta)}{\sqrt{\lambda\mu}},$$

in which $\alpha(\beta) = \left[\beta + \beta^2 \Phi(\beta) / \phi(\beta)\right]^{-1}$, while $\Phi(\beta)$ and $\phi(\beta)$ are the CDF and PDF, respectively, of a standard normal distribution.

The following lemma will be used to show that in a two-level system, the optimal staffing decisions and the optimal threshold are unique. All proofs are in Appendix B.

Lemma 1 If $C_w > 0$, the optimal standardized excess capacity β^* satisfies $d(\alpha(\beta))/d\beta|_{\beta=\beta^*} = -C_n/C_w$ and is strictly increasing in C_w .

4.2 The First-Best Solution

By applying the square root staffing rule, we staff the gatekeeper subsystem with $n_g^*(k, C_w) = \rho_g + \beta_g^*(C_w)\sqrt{\rho_g}$ and the expert subsystem with $n_e^*(k, C_w) = \rho_e + \beta_e^*(C_w)\sqrt{\rho_e}$, where β_g^* and β_e^* are the optimal standardized excess capacities for the gatekeeper and expert subsystems. Furthermore, from Lemma 1, we know that β_i^* satisfies

$$\frac{d}{d\beta}\alpha(\beta)\Big|_{\beta=\beta_i^*(C_w)} = -\frac{C_i}{C_w},\tag{3}$$

for $i \in \{e, g\}$. The quantities β_g^* and β_e^* are parameterized by C_w because, later in the paper, the waiting costs for the gatekeeper or expert subsystem may depend on the contract terms.

Given expressions for $n_g^*(k, C_w)$ and $n_e^*(k, C_w)$, the client's cost function can be reduced to a function of k,

$$\pi_c(k) = C_m \lambda(k - F(k)) + C_g \rho_g \left[1 + 2\Theta_g(k, C_w) \right] + C_e \rho_e \left[1 + 2\Theta_e(k, C_w) \right], \tag{4}$$

where $\Theta_i(k, y) = \eta_i(y)/(2\sqrt{\rho_i})$ and $\eta_i(y) = \beta_i^*(y) + (y/C_i) \alpha(\beta_i^*(y))$ for $i = \{e, g\}$. Note that as the arrival rate increases, the function $\Theta_i(k, y)$ approaches zero.

Lemma 2 guarantees the strict convexity of the cost function with respect to the treatment threshold. In addition, the lemma ensures the uniqueness of the optimal threshold, which also leads to the uniqueness of the optimal staffing, $n_g^*(k, C_w)$ and $n_e^*(k, C_w)$, because under Lemma 1, the optimal standardized excess capacities $\beta_g^*(C_w)$ and $\beta_e^*(C_w)$ are unique, given the customer flows implied by k^* .

Lemma 2 $\pi_c(k)$ is a strictly convex function in k if (1) $\lambda > \tilde{\lambda}_c$ and (2) $\partial^2 T_e(k)/\partial k^2 > 0$ for all k, in which $\tilde{\lambda}_c = t_g^4 \mu_g^3 C_g^2 \eta_g^2(C_w)/16H_c^2$, and $H_c = -C_m f'(k^*) - C_e V(k^*) - C_e \eta_e(C_w) t_e^2 f^2(k^*)/4T_e^{3/2}$.

The first condition places a lower bound on the arrival rate and is not related to the requirements of the QED regime. In our numerical examples, we find that this condition is easy to satisfy. For example, given the cost and capacity parameters for the numerical experiments in Section 5.3 we find that $\tilde{\lambda}_c$ is so low that only one server is needed to staff a system with such an arrival rate.

The second condition, requires convexity of $T_e(k)$. Recall that $T_e(k)$ is the expert treatment time averaged over all customers, including customers treated by the gatekeeper who have an expert treatment time equal to 0. To examine the implications of this condition, assume that $t_e(x) = \overline{t}_e(1 + x\Delta_e), \Delta_e > 0$, and f(x) = 1 - bx, b > 0. Then $\partial^2 T_e(k)/\partial k^2 > 0$ if $\Delta_e < b$, because

$$\frac{t'_e(k)}{t_e(k)} = \frac{\overline{t}_e \Delta_e}{\overline{t}_e(1+k\Delta_e)} \le \Delta_e < b \le \frac{b}{1-bk} = \frac{-f'(k)}{f(k)}.$$

This implies that the relative increment of the expert's treatment time (Δ_e) cannot be higher than the decrement of the gatekeeper's ability to successfully treat a customer (b). This would be consistent with situations in which lack of skill or knowledge cannot be completely compensated for by extra time spent with a customer.

Lemma 2 allows us to find the optimal threshold k^* by setting the first derivative of the client's cost to zero. The result is that $k^* = f^{-1}(r^*)$, in which

$$r^* = \frac{C_m + C_g t_g (1 + \Theta_g(k^*, C_w))}{C_m + C_e t_e (1 + \Theta_e(k^*, C_w))}.$$
(5)

Because the treatment function f is continuous, by the fixed-point theorem, the solution k^* exists.

From Equation (5), we see that when the expert's cost increases, the gatekeeper's cost decreases, or the mistreatment cost decreases, the optimal threshold k^* increases. However, it is less obvious how k^* changes with the waiting cost. Lemma 3 gives conditions for when the optimal threshold decreases with the unit waiting cost.

Lemma 3 k^* is strictly decreasing with respect to C_w if (1) $\lambda > \tilde{\lambda}_c$ and (2) $t_g > \tilde{\alpha}t_e$, in which $\tilde{\alpha} = (f(k^*)/\sqrt{\mu_g T_e})(\alpha(\beta_e^*(C_w))/\alpha(\beta_g^*(C_w))).$

The first condition again places a lower bound on the arrival rate, while the second condition requires that the gatekeeper's treatment time is longer than the expert's treatment time by a certain amount. We can show that $\tilde{\alpha}$ is not restrictive in our numerical examples.

Denote the optimal threshold in Shumsky and Pinker (2003) as $k_d^* = f^{-1}(r_d^*)$, in which $r_d^* = (C_m + C_g t_g) / (C_m + C_e t_e)$ with the subscript *d* indicating their paper's deterministic assumption for the arrival and service time distributions. The expression for our optimal threshold k^* has a form similar to k_d^* with the factor $C_i t_i$ replaced by $C_i t_i (1 + \Theta_i(k^*, C_w))$ for $i = \{e, g\}$. Because both $\Theta_g(k^*, C_w)$ and $\Theta_e(k^*, C_w)$ decrease as λ rises, $\lim_{\lambda \to \infty} k^* = k_d^*$; for large stochastic systems, the optimal treatment threshold is close to the optimal threshold for a deterministic system.

5. Analysis of Outsourcing Contracts

In this section we examine scenarios in which the client outsources the service process to a vendor. We consider four outsourcing options: outsourcing the expert (S_e) , outsourcing the gatekeeper (S_g) , outsourcing both (S_b) , and outsourcing a one-level system with no gatekeepers involved. The vendor can accept the contract or reject it; we assume here that the vendor's reservation level is 0. The client would like to design an enforceable contract that minimizes her costs, while providing a non-negative profit to the vendor. We are also interested in whether a particular contract achieves the system optimum or first best, the lowest cost achieved when decisions are centralized and when using the lowest wage rates of both client and vendor.

The terms of the outsourcing contract depend upon the information available to the client. There are two types of information in our gatekeeper model, *static* and *dynamic* information. By definition, static information does not change over the length of the contract. We assume that the model's parameters are static, i.e., customer arrival rates, service times for each level of call complexity, and the probability of a mistreatment for each type of call do not change. Dynamic information may change during the contract, sometimes rapidly. Dynamic information includes the arrival times and treatment complexities of particular customers in the system and whether particular customers are mistreated. We also assume that the internal decisions of the vendor are dynamic, for the vendor may choose to change referral rates and staffing levels over time.

We assume that the client has perfect knowledge of all static information. In some environments this is a limitation of our model, but clients often obtain estimates of the vendor's system parameters from third-party outsourcing consultants (e.g., Mackie, 2007) or from business information firms (e.g., www.datamonitor.com) that examine the performance of peer-groups of competing vendors. The client may also obtain static information by closely monitoring the vendor during previous contracts or during a trial period before the final contract is signed. Certainly, obtaining accurate information is not always possible. As Mackie (2007) writes, a benchmarking study to obtain parameter estimates is possible for "any service that has a low level of variability, a maturity of specification and a strong market for competitive supply." Our model applies to such services, while in other environments there may be significant information asymmetry between the client and vendor (Hasija et al., 2008; Ren and Zhang, 2009).

In this paper we do limit the amount of dynamic information that is available to the client. Specifically, when the client outsources a component of the system, or the entire system, we assume that the client only observes customer workflows into and out of the vendor, but does not observe the workflows or decisions inside the vendor's facility such as staffing levels, internal queue lengths, or internal referral rates. In other words, the contract terms are based only on data observable through standard, external technology such as a telecommunications switch. Such contracts are particularly inexpensive to enforce. Some contracts, such as revenue and cost-sharing contracts, do require information about the vendor's internal decisions, and therefore we do not analyze such contracts in this paper. Specifically, our contracts are based upon the number of customers handled by the vendor (corresponding to a pay-per-service incentive), the customer's total time in system with the vendor (corresponding to a system-time penalty), and whether a customer has been satisfactorily served by the vendor (corresponding to a pay-per-solve incentive). The client, however, continues to bear the costs of customer delays and mistreatment. Finally, in this section we assume that the choice of the overall system structure (a one-level or two-level system) is observable to the client and is contractible. In Section 6 we allow the vendor to choose the structure.

Now we identify contracts that achieve first best for systems S_e , S_g and the one-level system. These systems are generalizations of those described in Hasija et al. (2008) and Shumsky and Pinker (2003) and therefore we describe these results only briefly. Then we focus on the S_b system.

5.1 Systems S_e and S_g and the one-level system

In system S_e , the client outsources the expert subsystem to the vendor, who receives a payment from the client for the treatments performed. Meanwhile, the client operates the gatekeeper subsystem and sets the gatekeeper staffing level, the treatment threshold, and the contract. Similarly to Hasija et al. (2008) it can be shown that a pay-per-service contract (P^e) with a system-time penalty (Q^e) will achieve the centralized solution. The specific contract terms are given in the following proposition. **Proposition 1** A contract with system-time-penalty + pay-per-service components coordinates the system if the client offers the contract $(Q^e, P^e) = (C_w, C_e \rho_e [1 + 2\Theta_e(k^*, C_w)] / \lambda_e + C_w T_e(k^*) / (1 - F(k^*))).$

In system S_g , the client outsources the gatekeeper subsystem to the vendor, who receives a payment from the client and sets the number of gatekeepers and the treatment threshold. The client determines the staffing level for the expert subsystem, given the flow of referrals from the vendor. We consider a contract in which the client pays the vendor for each customer handled (payper-service, P^g) and a reward for the treatments that are successfully performed by the gatekeepers (pay-per-solve, R^g), and also applies a system-time penalty (Q^g). We assume that the vendor cannot deny that a customer was mistreated, block access to the client's experts, and collect the reward for treatment. Given that a customer recognizes mistreatment because the customer's problem has not been solved, such behavior will lead to a high level of customer dissatisfaction. A client firm will hear about this poor service directly from customers or from customer surveys, and we assume here that fear of exposure and loss of future business will prevent the vendor from this deception.

Lemma 4 $\pi_v^g(k)$ is strictly concave if $\lambda > \tilde{\lambda}_g$, in which $\tilde{\lambda}_g = t_g^4 \mu_g^3 C_g^2 \eta_g^2 (Q^g) / 16 H_g^2$ and $H_g = -f'(k) R^g + Q^g t'_g + C_g \lambda t'_g$.

As noted before, the condition $\lambda > \widetilde{\lambda}_g$ is very mild.

Proposition 2 A contract with system-time-penalty + pay-per-service + pay-per-solve components coordinates the system if the client offers $(Q^g, P^g, R^g) = (C_w, C_g \rho_g [1 + 2\Theta_g(k^*, C_w)] / \lambda - F(k^*) R^g + C_w (1/\mu_d + T_g), t_g [C_w + C_g (1 + \Theta_g(k^*, C_w))] / r^*).$

 Q^g ensures that the vendor staffs optimally when $k^g = k^*$, R^g ensures that $k^g = k^*$, and finally P^g ensures that the client extracts all the vendor's profit while the vendor is still willing to accept the contract.

Finally, when gatekeepers are relatively expensive, a one-level system with experts only is optimal. If the client outsources a one-level system, the contract is similar to the one in system S_e , i.e., a pay-per-service contract (P^1) with system-time penalty (Q^1). Corollary 1 describes the contract, which follows directly from Proposition 1.

Corollary 1 A contract with system-time-penalty + pay-per-service components coordinates the system if the client offers the contract $(Q^1, P^1) = (C_w, C_e \rho_e (1 + 2\Theta_e(0, C_w)) / \lambda + C_w T_e(0))$.

5.2 System S_b

The most interesting and challenging outsourcing problem is posed by S_b , the system in which both gatekeepers and experts are outsourced. In this case the vendor's choice of treatment threshold (or referral rate), gatekeeper staffing level, and expert staffing level are not directly observed by the client. In addition, customer mistreatments cannot be directly observed, for the client sees only a stream of successfully treated customers leaving the vendor's system. Under these conditions, we find that there can be a significant coordination cost to the client.

In system S_b , the only two measures observed by the client are the rate of customers served and the time in system. Therefore, we consider here a pay-per-service contract with a linear system-time penalty. Denote P^b as the payment per complete treatment and Q^b as the system-time penalty (\$/time/customer), which penalizes the total time in service, with mean $t(k) = 1/\mu_d + T_e + T_g$, and the time in queue, with mean $W_g + (1 - F(k))W_e$. The transfer payment from the client to the vendor is proportional to the number of services completed less the system-time penalty, i.e., $\lambda \left[P^b - Q^b[t(k) + W_g + (1 - F(k))W_e]\right]$. Consequently, the vendor's profit is,

$$\pi_v^b(n_g, n_e, k) = P^b \lambda - Q^b \lambda t(k) - \left(C_g n_g + Q^b W_g \lambda\right) - \left(C_e n_e + Q^b W_e \lambda_e\right).$$
(6)

As we did in the previous sections, we apply the square root staffing rule and simplify the vendor's profit to $\pi_v^b(k)$, a function of k. Lemma 5 describes conditions for the strict concavity of $\pi_v^b(k)$.

Lemma 5 $\pi_v^b(k)$ is a strictly concave function in k if $(1) \lambda > \widetilde{\lambda}_b$ and $(2) \partial^2 T_e(k) / \partial k^2 > 0$ for all k, in which $\widetilde{\lambda}_b = t_g^4 \mu_g^3 C_g^2 \eta_g^2(Q^b) / 16H_b^2$ and $H_b = -(Q^b + C_e) V(Q^b) + Q^b t'_g - C_e \eta_e(Q^b) t_e^2 f^2(k) / 4T_e^{3/2}$.

As in Lemma 2, the conditions specify a minimum arrival rate as well as characteristics of the treatment functions. Again, we have found numerically that neither condition is restrictive.

By optimizing $\pi_v^b(k)$ over k, we find that when the vendor is offered contract (Q^b, P^b) , the vendor chooses threshold $k^b = f^{-1}(r^b)$,

$$r^{b} = \frac{t_{g}}{t_{e}} \frac{Q^{b} + C_{g} \left(1 + \Theta_{g}(k^{b}, Q^{b})\right)}{Q^{b} + C_{e} \left(1 + \Theta_{e}(k^{b}, Q^{b})\right)}.$$
(7)

It is useful to compare this threshold condition with Equation (5), the condition that defines the first-best treatment threshold. When moving from r^* to r^b , the mistreatment cost C_m is replaced by $t_g Q^b$ and $t_e Q^b$, and the waiting cost C_w is replaced by Q^b . This implies that in system S_b , the system-time penalty Q^b must serve two roles for the client. Because the system-time penalty penalizes waiting times in both queues, Q^b serves as a congestion cost to the vendor. On the other hand, because mistreated requests are treated twice and therefore increase time in service, Q^b also serves as a mistreatment penalty. In this case, Q^b affects k^b directly. Lemma 6 describes the relationship between k^b and Q^b : if the conditions of the lemma are satisfied, the direct effect of the mistreatment penalty dominates and the threshold k^b decreases with Q^b .

Lemma 6 If (1) $\lambda > \tilde{\lambda}_b$ and (2) $\partial^2 T_e(k) / \partial k^2 > 0$ for all k, and (3) $t_g \ge \max(1, \tilde{\alpha}) t_e$ for $0 \le k \le 1$, then k^b is strictly decreasing with Q^b .

Conditions 1 and 2 guarantee the concavity of the vendor's profit function; Condition 3 requires a system in which the gatekeeper's treatment time is longer than the expert's treatment time. Proposition 3 describes the conditions on Q^b and the system parameters for which the contract can coordinate the system.

Proposition 3 A contract with system-time-penalty + pay-per-service components, (Q^b, P^b) , coordinates the system if and only if

$$Q^{b} = C_{w} = \frac{f(k^{*})C_{e}t_{e}\left(1 + \Theta_{e}(k^{*}, C_{w})\right) - C_{g}t_{g}\left(1 + \Theta_{g}(k^{*}, C_{w})\right)}{t_{g} - f(k^{*})t_{e}}$$

We refer to the condition on Q^b in Proposition 3, as the *coordination condition*. If it is satisfied then system S_b can achieve the system optimum. Corollary 2 describes how C_m and C_w relate to each other within the coordination condition. The corollary provides intuition as to what causes inefficiency in system S_b ; we will reinforce this intuition with numerical experiments in the next section.

Corollary 2 The mistreatment cost C_m that satisfies the coordination condition increases with the waiting cost C_w if (1) $\lambda > \tilde{\lambda}_c$, (2) $t_g \ge \max(1, \tilde{\alpha})t_e$ for $0 \le k \le 1$, and (3) $t'_g \le (t_g - t_e)(-f'(k^*)) / (1 - f(k^*)) + t'_e f(k^*)$.

The corollary implies that if the mistreatment and waiting costs are aligned, it may be easier to achieve coordination. The relationship between C_m and C_w follows only if all three conditions are satisfied. Specifically, Condition 1 again requires a large enough arrival rate; Conditions 2 and 3 require the gatekeepers to be slower than the experts. For example, if $t_g(x) = \bar{t}_g(1 + x\Delta_g)$, $t_e(x) = \bar{t}_e(1 + x\Delta_e)$, and f(x) = 1 - bx, Condition 2 ($t_g \ge \max(1, \tilde{\alpha})t_e$) is not sufficient and we need Condition 3, which reduces to $\bar{t}_g \ge \bar{t}_e(1 + b\Delta_e)$.

Next we discuss the contract the client offers when the coordination condition is not satisfied. The client pays the vendor for the services that he provides and incurs the waiting and mistreatment costs, yielding the following objective:

$$\pi_c^b(Q^b, P^b) = C_m \lambda(k^b - F(k^b)) + P^b \lambda - Q^b \lambda t(k^b) + \left(C_w - Q^b\right) \left(\alpha(\beta_g^*) \sqrt{\rho_g} + \alpha(\beta_e^*) \sqrt{\rho_e}\right),$$

in which $\beta_i^*(Q^b)$ is abbreviated to β_i^* for $i \in \{e, g\}$. From Equation (7), we know that the threshold k^b only depends on the value of Q^b but not P^b . Consequently, for a given Q^b , the client's cost increases with P^b , and thus she prefers to lower the value of P^b . However, P^b has to be sufficiently high so that the vendor will accept the contract. As a result, she offers a P^b that gives the vendor zero profit,

$$P^{b} = Q^{b}t(k^{b}) + \frac{1}{\lambda} \left\{ C_{e}\rho_{e} \left[1 + 2\Theta_{e}(k^{b}, Q^{b}) \right] + C_{g}\rho_{g} \left[1 + 2\Theta_{g}(k^{b}, Q^{b}) \right] \right\}.$$

The client's cost is therefore only a function of Q^b ,

$$\pi_c^b(Q^b) = C_m \lambda(k^b - F(k^b)) + \left(C_g n_g + C_w \alpha(\beta_g^*(Q^b))\sqrt{\rho_g}\right) + \left(C_e n_e + C_w \alpha(\beta_e^*(Q^b))\sqrt{\rho_e}\right).$$

Note that the congestion cost is C_w for the client, but is Q^b for the vendor.

Proposition 4 describes the complete client-optimal contract (Q^b, P^b) , given $\lambda > \tilde{\lambda}^b_*$. As for the other arrival rate lower bounds, this condition is not restrictive.

Proposition 4 Assume that $\lambda > \tilde{\lambda}_*^b$. The client offers a contract $(Q^b, P^b) = (Q^b_*, P^b_*)$, in which

$$Q_*^b = \left[C_e t_e \left[1 + \Theta_e(k_*^b, Q_*^b) \right] r_*^b - C_g t_g \left[1 + \Theta_g(k_*^b, Q_*^b) \right] \right] / [t_g - r_*^b t_e], \text{ and}$$
$$P_*^b = Q_*^b t(k_*^b) + \left[C_e \rho_e \left[1 + 2\Theta_e(k_*^b, Q_*^b) \right] + C_g \rho_g \left[1 + 2\Theta_g(k_*^b, Q_*^b) \right] \right] / \lambda,$$

and the vendor sets the threshold at $k^b = k^b_* = f^{-1}(r^b_*)$, in which $r^b_* = (C_m + C_g t_g (1 + \Psi_g(k^b_*))) / C_m + C_e t_e (1 + \Psi_e(k^b_*))$, $\Psi_i(k) = \tilde{\eta}_i(Q^b) / [2\sqrt{\rho_i}]$ and $\tilde{\eta}_i(Q^b) = \beta^*_i(Q^b) + C_w \alpha(\beta^*_i(Q^b)) / C_i$, for $i \in \{e, g\}$, $\tilde{\lambda}^b_* = t^4_g \mu^3_g C^2_g \tilde{\eta}^2_g (Q^b_*) / 16 (H^b_*)^2$, and $H^b_* = -C_m f'(k^b_*) - C_e V(Q^b_*) - C_e \tilde{\eta}^2_e (Q^b_*) t^2_e f^2(k^b_*) / 4T_e^{3/2}$.

Because $k_c^b \neq k^*$, the client pays more than the system optimum, $\pi_c(k^*)$. If the vendor does not provide cost advantage(s) to the client, the client will not outsource.

The following two propositions describe the relationships among the costs C_w and C_m and the optimal solutions k_*^b and Q_*^b . First, when we increase the waiting cost, it is intuitive that the client would raise the system-time penalty to enforce higher staffing levels. Therefore, when the client increases the system-time penalty, the optimal threshold k_*^b decreases as well, because to the vendor, the mistreatment cost increases.

Proposition 5 Given the conditions of Lemma 2 and Proposition 4, Q_*^b increases with C_w and k_*^b decreases with C_w .

Proposition 5 implies that as C_w increases, the total mistreatment cost in the system declines because a lower k_*^b implies fewer gatekeeper treatment attempts, and therefore lower mistreatment costs. Proposition 6 shows how the mistreatment cost parameter affects the optimal system-time penalty and the optimal threshold.

Proposition 6 Given the conditions of Lemma 2 and Proposition 4, Q^b_* increases with C_m and k^b_* decreases with C_m .

Proposition 6 implies that as C_m increases, the mean customer waiting time in the system declines because a higher Q_*^b will lead to greater staffing by the vendor and shorter queueing times. In addition, a lower k_*^b implies fewer gatekeeper treatment attempts, and therefore less time spent with the gatekeeper.

5.3 Numerical Examples

In this section we use numerical experiments to explore the costs and benefits of each outsourcing contract assuming the vendor does not deviate from the client's preferred system structure. We focus on the implications of Proposition 3 and Corollary 2 and examine how outsourcing both components can lead to system inefficiency and higher costs for the client. In Section 6.2 we will use the same setup to investigate which outsourcing option the client would choose in a variety of environments while also accounting for vendor deviation from the client's preferred system structure. Throughout both sections we use the following parameters: $\lambda = 100$ customer requests per minute, $\mu_d = 2$ per minute, $1/\bar{t}_g = 2/3$ per minute, $\Delta_g = 0, 1/\bar{t}_e = 1.5$ per minute, $\Delta_e = 0, C_g = \$10$ per gatekeeper per hour, and f(x) = 1 - x. The parameters were chosen so that (1) a two-level structure outperforms a one-level structure for a majority of the experiments; and (2) the size of the system in each experiment is reasonably within the QED regime. Specifically, with these parameters a one-level system would have a load equivalent to 67 experts, while a two-level system with a treatment threshold k = 0.5 would have a load equivalent to 100 gatekeepers and 45 experts. The results described here are consistent with the results from experiments with many other parameter sets, including those with $\Delta_g > 0$ and $\Delta_e > 0$, so that treatment time is a function of problem complexity.

The solid line in Figure 2 shows the (C_w, C_m) pairs that satisfy the coordination condition defined in Proposition 3, given that $C_e = \$60$ per hour. As predicted by Corollary 2, the line increases. Proposition 3 indicates that systems with values of (C_w, C_m) close to the line (such as (6, 0.12) and (30, 0.8) - the (low,low) and (high, high) cases) should provide maximum profits



Figure 2: Waiting cost/mistreatment cost pairs that satisfy the coordination condition

for the client, while pairs far from the line ((6, 0.8) and (30, 0.12); (low, high) and (high, low)) should be less profitable. Note that the terms "low" and "high" describe the parameters' relative locations, and do not necessarily describe the absolute values of the parameters in any particular environment.

To illustrate Proposition 3, for each of the four parameter pairs in Figure 2 (and for a range of C_e from \$40 to \$80) we calculate the optimal thresholds for the centralized system and system S_b (k^* and k_*^b) and the optimal costs for both systems. Define the system *inefficiency* as the relative cost difference between the system optimum and the client's smallest possible cost in S_b , i.e., $\left|\pi_c^b(Q_*^b, P_*^b) - \pi_c(k^*)\right| / \pi_c(k^*)$. Figure 3A displays the system inefficiencies when C_w is low (\$6), and Figure 3B displays the results when C_w is high (\$30) (note that the plots have a log scale on the y-axis). As predicted, when (C_w, C_m) is far from the coordination condition, e.g., (low, high) in Figure 3A or (high, low) in Figure 3B, the client-optimal contract is inefficient, up to 6% in this case. Conversely, the inefficiency is relatively low (under 0.2%) when C_m and C_w are both low (3A) or both high (3B).

We now explore the implications of these results by examining the thresholds chosen by the vendor and by decomposing the costs to determine the sources of system inefficiency. Figure 4A shows the optimal thresholds when $C_w = \$30$ per hour and $C_m = \$0.12$ (high, low), and Figure 4B shows thresholds when $C_w = \$30$ per hour and $C_m = \$0.8$ (high, high). The solid lines represent the optimal thresholds for the first-best solution, k^* , and the dashed lines represent the optimal thresholds for system S_b , k_*^b .

As predicted by Proposition 6, k_*^b falls as we move from Figure 4A to Figure 4B and C_m rises.



Figure 3: Inefficiency in system S_b



Figure 4: The optimal thresholds for the first-best solution and system S_b when $C_w = 30 per hour and (A) $C_m = 0.12 , (high, low) and (B) $C_m = 0.8 , (high, high)

We also see in Figure 4A that k_*^b can deviate significantly from k^* as we move off of the coordination condition. In this case, because the mistreatment cost is low, the client prefers a high threshold. To force the vendor to set the threshold at a high level, she offers a system-time penalty Q^b that is smaller than the high waiting cost in the centralized system, C_w . Lowering Q^b essentially lowers the mistreatment penalty to the vendor and pushes the vendor towards the client's desired k. Lowering Q^b , however, also reduces the cost of waiting for the vendor, and therefore the vendor reduces staffing levels and the client incurs higher congestion costs. Therefore, the client chooses a Q^b that does not quite drive k_*^b all the way up to k^* . Following the same logic, for the (low, high) system we would see a Q^b that is higher than C_w and a k_*^b that is higher than k^* . Figure 4 also shows the impact of changes in C_e , the cost of experts. In each figure, when experts are inexpensive, the client prefers a lower threshold and more referrals, and the preferred threshold rises as the experts' cost rises.

Now we decompose the system costs and see how each part changes when we outsource the system. Consider the (high, low) case, with $C_w = \$30$ per hour and $C_m = \$0.12$. From the analysis above, we would expect longer waiting costs when outsourcing, and this is confirmed in Figure 5. Figure 5A shows, for the centralized system, the gatekeeper's staffing cost, the expert's staffing cost, the mistreatment cost, and the client's expected total waiting cost, $C_w(W_g\lambda + W_e\lambda_e)$. Figure 5B shows similar costs in system S_b , with the client's total waiting cost separated into two components. The first component is the "vendor's waiting cost," $Q^b(W_g\lambda + W_e\lambda_e)$, the expected payment from the vendor to the client due to the system-time penalty. The second component is the "client's congestion cost," $(C_w - Q^b)(W_g\lambda + W_e\lambda_e)$, the cost of customer waiting-time above and beyond the system time penalty.

When looking from Figure 5A to B, we see visually that in this (high, low) environment, the primary increase in cost is due to additional waiting time: $C_w(W_g\lambda + W_e\lambda_e)$ rises by at least 263% (on the right-hand side, when C_e =\$80) and by at most 412% (when C_e = \$40). Figure 5B shows that most of this increase is paid for by the vendor, in the form of the system-time penalty, but that the residual "Client's congestion cost" remains substantial as well (the client's congestion cost after outsourcing is itself larger than the total cost due to waiting in the centralized system). Meanwhile, staffing costs decline somewhat (a decrease by at least 6% and by at most 9%), while mistreatment costs decline by from 29% to 52%. For this (high, low) case, mistreatment costs are reduced somewhat under outsourcing, but staffing is also reduced and customers suffer substantially longer delays.

Now consider the (low, high) system. From our previous analysis, we would expect that out-



Figure 5: Cost decomposition for (A) the centralized system and (B) system S_b

sourcing would lead to a rise in mistreatment costs. Indeed, mistreatment costs rise by 26% to 40%, while the total waiting-time cost declines by 181% to 148%. In this case, staffing costs also increase, by approximately 5% throughout the range in C_e from \$40 to \$80.

6. Vendor Process Choice and Outsourcing Decisions

Thus far we have assumed that the vendor complies with the client's process choice (expert only, two-level, one-level, etc.). There may be cases in which it is difficult for the client to monitor the vendor's process choice and therefore it is possible for the vendor to deviate from the client's preference. In this section we will account for the possibility of such behavior by the vendor. We will also use numerical experiments to explore the client's optimal outsourcing strategy in the presence of both vendor process choice and vendor staffing cost advantages.

6.1 Vendor Process Choice

First assume that the client wants to outsource the entire system (later we will discuss contracts for expert-only and gatekeeper-only systems). If the vendor offers a contract designed for a one-level (two-level) system, and under that contract the client chooses to operate a one-level (two-level) system, then we say that the contract is *incentive compatible*. Here we describe the client's optimal incentive-compatible contract. Let (Q, P) be the system-time penalty and pay-per-service payment

the client offers. The vendor's profit function if the vendor chooses a one-level process is:

$$\pi_{v}^{1}(Q, P) = P\lambda - QT_{e}(0)\lambda - C_{e}\rho_{e}(0)\left(1 + 2\Theta_{e}(0, Q)\right),$$

If he chooses a two-level process the vendor's profit is:

$$\pi_v^b(Q,P) = P\lambda - Qt(k(Q))\lambda - C_g\rho_g(k(Q))\left(1 + 2\Theta_g(k(Q),Q)\right) - C_e\rho_e(k(Q))\left(1 + 2\Theta_e(k(Q),Q)\right),$$

in which

$$f(k(Q)) = \frac{t_g(k(Q))}{t_e(k(Q))} \frac{Q + C_g(1 + \Theta_g(k(Q), Q))}{Q + C_e(1 + \Theta_e(k(Q), Q))}.$$

This equation implicitly defines k(Q) and only depends on Q but not P.

We first construct the vendor's individual rationality (IR) constraints for both process choices. A necessary condition for the vendor to accept the contract and choose a one-level process is that the pay-per-service payment satisfies $\pi_v^1(Q, P) \ge 0$, or equivalently,

$$P \ge P^{1}(Q) = QT_{e}(0) + C_{e}\rho_{e}(0) \left(1 + 2\Theta_{e}(0,Q)\right)/\lambda > 0.$$
(8)

A necessary condition for the vendor to accept the contract and choose a two-level process, is that the pay-per-service payment satisfies the IR constraint $\pi_v^b(Q, P) \ge 0$, or equivalently,

$$P \ge P^{b}(Q) = Qt(k(Q)) + \frac{C_{g}\rho_{g}(k(Q))}{\lambda} \left(1 + 2\Theta_{g}(k(Q), Q)\right) + \frac{C_{e}\rho_{e}(k(Q))}{\lambda} \left(1 + 2\Theta_{e}(k(Q), Q)\right) > 0.$$
(9)

The following lemma describes the space of possible contracts that the client may offer.

Lemma 7 For a given Q, the client only offers contract $(Q, \min(P^1(Q), P^b(Q)))$ to the vendor.

In Proposition 7 below we will describe the client's optimal incentive-compatible contract in terms of the points of intersection between the two IR constraints. But first, consider the case where the two IR constraints do not intersect. If $P^1(Q) < P^b(Q)$ for all Q, the vendor will always choose a one-level system and therefore an incentive compatible contract does not exist for a twolevel system. If $P^1(Q) > P^b(Q)$ for all Q, the vendor will always choose a two-level system and an incentive compatible contract does not exist for a one-level system.

At an intersection of the IR constraints where $P^1(Q) = P^b(Q)$, the vendor is indifferent between a one- and a two-level system, and we assume that the vendor chooses the process preferred by the client. Denote the N(> 0) intersections as $(Q_1, P_1), (Q_2, P_2), ..., (Q_N, P_N)$, in which $Q_1 < Q_2 <$ $... < Q_N < \infty$. Recall that the optimal contract for system S_b in Proposition 4 is (Q_*^b, P_*^b) , and for the one-level system in Corollary 1 is (Q^1, P^1) . Thus, we can find the two nearest adjacent intersections to (Q^b_*, P^b_*) and (Q^1, Q^1) , i.e., $Q_L < Q^b_* < Q_{L+1}$ and $Q_J < Q^1 < Q_{J+1}$.

Proposition 7 (A) The client's optimal and incentive compatible contract for system S_b is either (Q_*^b, P_*^b) , if $P_*^b \leq P^1(Q_*^b)$, or is (Q_L, P_L) or (Q_{L+1}, P_{L+1}) , if $P_*^b > P^1(Q_c^b)$. (B) The client's optimal and incentive compatible contract for the one-level system is either (Q^1, P^1) , if $P^1 \leq P^b(Q^1)$, or is (Q_J, P_J) or (Q_{J+1}, P_{J+1}) if $P^1 > P^b(Q^1)$.

This proposition implies that for system S_b , if the client anticipates that the vendor will not deviate from the client's choice, then the client will choose the contract in Proposition 4; if the vendor is expected to deviate from his choice, then it is optimal for the client to choose an incentive compatible contract that generates the lowest cost. This incentive compatible contract will be one of the two intersections that are nearest to (Q_*^b, P_*^b) . A similar logic applies when outsourcing a one-level system: either offer the contract in Corollary 1 or a contract located on one of the two nearest intersections of the IR constraints.

When the client intends to outsource an expert-only system as a one-level system, the client might choose to operate a two-level system by inserting an additional layer of gatekeepers. While an analysis similar to the one above may be used to find incentive-compatible expert-only contracts, in most cases inserting gatekeepers is not cost-effective for the vendor because many of the lowcomplexity customers have already been screened by the client's gatekeepers. In all of the numerical tests in the next section, the expert-only contracts were incentive-compatible, and in general we will assume that the vendor will not diverge from an expert-only contract. Finally, if the client intends to outsource a gatekeeper-only system, we assume that the client can monitor the vendor's choice. This monitoring can be done by observing the rate at which the vendor successfully treats customers, an activity the client must perform to execute the optimal contract in Proposition 2.

To summarize our results, the client's optimal contract is either (i) the contract in Proposition 1, in which the client chooses S_e , (ii) the contract in Proposition 2, in which the client chooses S_g , (iii) the incentive compatible contract in Proposition 7(A), in which the client chooses S_b , or (iv) the incentive compatible contract in Proposition 7(B), in which the client chooses a one-level system.



Figure 6: The outsourcing decision when (A) $C_m =$ \$0.12, (high, low), and (B) $C_m =$ \$0.8, (high, high)

6.2 Numerical Examples of Outsourcing Decisions

In this section we focus on which part(s) of the process to outsource, given that the vendor may, or may not, deviate from the client's preferred process. For the two-level structure to be considered by the client, the expert's cost must be high relative to the cost of the gatekeepers. Therefore, we set $C_g = \$10$ per gatekeeper per hour and $C_e = \$60$ per expert per hour. As in the (high, low) and (high, high) cases from Section 5.3, we set $C_w = \$30$ per customer per hour and $C_m = \$0.12$ or \$0.8 per mistreated customer. Because the best the vendor can do for the client is the system optimum, he has to provide staffing cost advantages, otherwise the client will keep the process in-house. We consider a vendor who offers a gatekeeper's cost of $C'_g = C_g(1 - \delta_g)$ and an expert's cost of $C'_e = C_e(1 - \delta_e)$, in which C_g and C_e are the client staffing costs and δ_g and δ_e represent the cost savings provided by the vendor. Given these cost advantages, we compute the optimal total cost for the client under each outsourcing scenario and then make the outsourcing decision for her by selecting the system that provides the lowest cost. The decisions when $C_m = \$0.12$ are shown in Figure 6A, while the decisions when $C_m = \$0.8$ are shown in Figure 6B.

In Figure 6, the solid lines delineate regions over which each process is optimal for the client when the process choice is contractible, so that the vendor does not deviate from the client's optimal process choice. The dotted lines delineate regions over which each process is optimal when vendors can deviate, and therefore the client uses the optimal incentive-compatible contracts described in the previous section. For example, when vendors can deviate, Figure 6A shows that an expertonly system should be outsourced over the region from $\delta_e = 0\%$ to 23% along the x-axis, up to the slanted dotted line above. In Figure 6B, the area specifying a one-level design is larger under vendor choice, and in the remaining area the client should outsource a two-level system when vendors do not deviate (the area labeled "Both (w/o choice)"), and should outsource gatekeepers only, with deviation ("Gatekeeper (w/ choice)").

Whether the vendor can deviate or not, it is no surprise that Figure 6A shows that when the vendor offers inexpensive gatekeepers and not-so-inexpensive experts (high δ_g and low δ_e), the client prefers S_g . When the vendor offers a low δ_g and a high δ_e , the client prefers S_e . Finally, when both δ_g and δ_e are high, she prefers S_b . When the expert is extremely inexpensive, e.g., $\delta_e \approx 23\%$, systems S_e and S_b are replaced by the one-level structure. Despite the potential contract inefficiency of S_b (see Figure 3), S_b may still be the optimal choice because it may provide staffing cost savings from both levels, while S_e or S_g only provides savings on one level.

When the vendor does not deviate from the client's preferred process, we find that system S_b is preferred over a wider range of vendor cost reductions when C_m and C_w are both relatively high. In fact, for the (high, high) case in Figure 6B, the 'Gatekeeper' and 'Expert' preference regions are not even visible. Outsourcing the gatekeeper or the expert alone is preferred over a wider range when C_m is low and C_w is high - the (high, low) case in Figure 6A. When a coordinating (or nearly-coordinating) contract exists for S_b for particular parameter combinations, e.g., when C_m and C_w are aligned, the slight labor cost savings offered by the vendor are sufficient to motivate the client to outsource both levels.

Now consider the impact of vendor deviation from the client's optimal process choice. Suppose that the process choice is not contractible and that the client does not anticipate deviation; she only offers the contracts derived in Section 5. We find that the loss in client profits can be quite large. In Figure 6A, the vendor will choose to deviate from S_b over the entire region labeled "Both." In this region, if the client offers the contracts defined by Proposition 4 and the process choice is not contractible, the vendor will choose to operate a one-level system, resulting in costs to the client that are up to 36% larger than the system with no deviation. Similar deviations in Figure 6B can be even more costly, up to 47% larger.

If the client anticipates deviation, she can identify the new optimal outsourcing choices, as defined by the dotted lines in Figure 6. In these examples, the two-level contracts must be adjusted to be incentive compatible, as in Proposition 7. Therefore, the coordination cost for system S_b rises, and the regions over which S_b is optimal shrinks. The difference between the client costs with no vendor deviation and the client costs under the incentive-compatible contracts is the break-even cost of monitoring and enforcing the vendor's process choice. In both Figures 6A and B, we find that this break-even monitoring cost ranges from 0 to as high as 6%. Offering incentive-compatible contracts significantly reduces, but does not eliminate, the cost of vendor process deviation.

7. Model Extensions

7.1 Gatekeeper Misdiagnosis

We have thus far assumed that the gatekeeper can perfectly diagnose the complexity of a case. Relaxing that assumption will not alter our main results. Suppose that the gatekeeper diagnoses a case as having complexity \hat{x} but because of misdiagnoses the true complexity, x, has a probability density of $g(x, \hat{x})$. In that case the probability of being treated correctly is given by:

$$\hat{f}(\hat{x}) = \int_0^1 f(x)g(x,\hat{x})dx.$$

If we make the reasonable assumption that for $\hat{x}_1 > \hat{x}_2$, $g(x, \hat{x}_1)$ stochastically dominates $g(x, \hat{x}_2)$, then $\hat{f}(\hat{x})$ is decreasing in \hat{x} , and we can replace f(x) and F(x) in our model accordingly. Similarly we can revise the expected treatment time functions as follows:

$$T_g(k) = \int_0^k \int_0^1 t(y)g(y,\hat{x})dyd\hat{x}.$$

Therefore given a misdiagnosis function $g(x, \hat{x})$ we can redefine all the treatment success and treatment time functions without changing our analytical results.

7.2 Expert Mistreatment

In some settings both gatekeepers and experts may mistreat customers, so that a customer may leave the system without successful treatment. In this section we will show that under certain conditions we can convert the objective function of such systems into a form equivalent to Equation (4), preserving the results presented above.

Let $f_i(x)$, $i \in \{g, e\}$, be the probability that a type *i* worker successfully treats a problem with complexity *x*. Assume that functions $f_i(x)$ are continuous and differentiable, $f_g(x) \leq f_e(x)$ and, as before, the treatment probability declines with problem complexity so that $f'_i(x) < 0$. Let C^i_m be the cost per mistreatment caused by worker type *i*.

We will incorporate $f_e(x)$ into the previous model, but first we must define the relationship between f_g and f_e for each problem of complexity x. Define the random variable z_i , $i \in \{g, e\}$, to indicate mistreatment by a gatekeeper or expert:

$$z_i = \begin{cases} 0 \text{ if } i \text{ successfully treats} \\ 1 \text{ if } i \text{ mistreats} \end{cases}$$

Let $\overline{f}_i(x) = 1 - f_i(x)$. Therefore, $E(z_i|x) = \overline{f}_i(x)$, and the covariance between z_g and z_e for a

problem with complexity x is,

$$cov(z_g, z_e|x) = E\left[\left(z_g - \overline{f}_g(x)\right)\left(z_e - \overline{f}_e(x)\right)|x\right]$$
$$= \Pr\left\{z_g = 1, z_e = 1|x\right\} - \overline{f}_g(x)\overline{f}_e(x)$$
$$= \Pr\left\{z_g = 1|z_e = 1, x\right\}\overline{f}_e(x) - \overline{f}_g(x)\overline{f}_e(x).$$

Define $\psi(x) = \Pr \{z_g = 1 | z_e = 1, x\}$. The quantity $\psi(x)$ is the probability that the gatekeeper mistreats a customer of complexity x, given that an expert would mistreat the customer if the customer is referred to the expert. Of course, we assume that $0 \leq \psi(x) \leq 1$, and these bounds correspond to lower and upper bounds on the covariance between gatekeeper and expert mistreatment. At the upper bound $\psi(x) = 1$ the covariance is positive, and if an expert mistreats, then so would the gatekeeper. This implies that experts are uniformly superior to gatekeepers. At the lower bound $\psi(x) = 0$, the covariance is negative, and it is possible that the gatekeeper a customer encounters can successfully treat a problem, while an expert would have failed.

In the client's cost function (Equation 4), the expected cost of mistreatment per customer, given treatment threshold k, is $C_m(k - F(k))$. Given that experts can mistreat as well, we can rewrite this cost as,

$$C_m^g \int_0^k \overline{f}_g(x) dx + C_m^e \left(\int_0^k \psi(x) \overline{f}_e(x) dx + \int_k^1 \overline{f}_e(x) dx \right),$$

where the first term is the cost of mistreatment by the gatekeeper, the second term is the cost of mistreatment by both the gatekeeper and the expert, and the third term is the cost of mistreatment by the expert for customers who are referred directly to the expert. This expression is equivalent to,

$$C_m^e \left(1 - \int_0^1 f_e(x) dx\right) + C_m^g \left(k - \int_0^k f_g(x) dx\right) + C_m^e \int_0^k \left(\psi(x) + (1 - \psi(x)) f_e(x) - 1\right) dx.$$
(10)

Note that the first term of this expression does not depend upon the treatment threshold k, so that given parameters C_m^e and $f_e(x)$, it is a constant.

Now redefine $C_m = C_m^g$ and

$$f(x) = f_g(x) - \frac{C_m^e(\psi(x) + (1 - \psi(x)) f_e(x) - 1)}{C_m^g}.$$
(11)

As before, let $F(k) = \int_0^k f(x) dx$. Given these definitions, the mistreatment cost $C_m (k - F(k))$, from Equation (4) differs from (10) only by the constant first term. Therefore, by applying $C_m = C_m^g$ and (11), all of the previous results continue to hold when experts, as well as gatekeepers, mistreat.

Finally, we must make sure that the newly-defined f(x) in (11) is a valid treatment function. For example, assume that (i) $\psi(x)$ is a constant, ψ , for all x, (ii) $C_m^g = C_m^e$,(iii) the gatekeeper treatment function is $f_g(x) = 1 - x$, and (iv) the expert treatment function $f_e(x) = 1 - bx$. Because $f'_g(x) < 0$ and $f'_e(x) < 0$, we know that f'(x) < 0, if $b \leq 1$ for all $0 \leq \psi \leq 1$. The additional constraints $0 \leq f(x) \leq 1$, however, do limit the parameter sets that will produce valid functions. It can be shown for this example that the condition $f(x) \geq 0$ for $0 \leq x \leq 1$ is satisfied only if $\psi = 1$. In general, our transformation will be valid for larger sets of parameters when ψ is closer to 1, and gatekeepers are more likely to mistreat when experts mistreat as well.

7.3 Additional Variations and Extensions

Depending on the business environment, the structure of gatekeeper systems and outsourcing decisions may be driven by factors that are not included in the model described above. First, in our model, we only consider customers with infinite patience, while in many systems customers do abandon the queue. Additional analysis in — (2009) of outsourced systems with customer abandonment produces results similar to those described above. — (2009) identifies similar system-coordinating contracts under S_e and S_g , and shows that under S_b a coordinating contract does not exist unless the environment satisfies a similar coordination condition.

Second, in some environments the client may be penalized by a customer for total system time, while in the model above she is penalized for waiting time. For example, when outsourcing a back-office process, customers are not physically present in the system, and therefore customers only observe (and care about) total system time. The analysis of such systems under S_e and S_g is virtually the same as the analysis above. Under S_b , we consider two variations: a process with non-trivial mistreatment cost and one with trivial mistreatment cost. For the former, there is again no coordinating contract unless the exogenous parameters satisfy a coordinating condition. When mistreatment costs are trivial (e.g., if the customer is not aware that the gatekeeper has tried, and failed, to handle the job), then a coordinating contract does exist under S_b because both the client and the vendor are only penalized for total system time, and therefore their incentives are aligned. The model would predict that back-office processes with insignificant mistreatment costs are generally outsourced as a whole, rather than in parts.

Third, there exists environments in which the waiting costs for the gatekeeper and the expert subsystems are not identical. This does not significantly change our analysis of the centralized system, system S_e , or system S_g . In each case, simply replace the common waiting cost C_w with the appropriate subsystem-specific waiting cost. For system S_b , however, the client only observes total system time and cannot distinguish between waiting times for gatekeepers and waiting times for experts in the contract. Therefore, as we found with a common waiting cost C_w , a contract with only pay-per-service and system-time-penalty components cannot coordinate the system.

Fourth, a client may outsource the two subsystems to two different vendors. If the client can observe the gatekeeper vendor's referral rate, the problem reduces to two separate S_g and S_e systems, and we have seen that contracts exist to coordinate each system. If the client cannot observe the flow of referrals, e.g., if the telecommunications switch between the two vendors is controlled by a third-party, then it is not possible to coordinate the system with separate contracts to each vendor.

Fifth, we have assumed that for a problem with a given value of x, both the treatment time and probability of success are exogenous, so that there is no endogenous trade-off between the gatekeeper's probability of success f(x) and the mean gatekeeper treatment time $t_g(x)$. In our model, we assume the existence of some fundamental knowledge or skill that is required to treat a customer; once all relevant information is collected from the customer extra time will not improve the gatekeeper's chances. We also assume that an agent does not have the option to adjust a particular customer's service time in response to system-time penalties. We believe that such an assumption is appropriate for technical support and many health care applications, where the agents may, or may not, have a particular type of training or previously seen a particular case and there are a clear set of steps, e.g., a script, to follow when attempting to solve a problem. In general, the trade-off between treatment time and service success is an interesting area of study (e.g., see de Véricourt and Sun, 2009), but is beyond the scope of this paper.

8. Conclusions

This paper investigates how a client may make outsourcing decisions for service processes with a two-level structure, in which the first level serves as a gatekeeper for the second level of experts. The model in this paper allows us to analyze the interrelationships between staffing and workflow decisions in an outsourcing context.

We find that with easily-observable measures (e.g., output rates and total system times), optimal contracts that achieve the system optimum exist when outsourcing a one-level system and when outsourcing a single subsystem of a two-level system. An optimal contract does not exist, however, when the client outsources both levels to a vendor, unless a particular coordination condition is satisfied. Thus some degree of system inefficiency may arise for this outsourcing option. We also describe client-optimal contracts when vendors may deviate from the client's system choice, but such deviation introduces additional inefficiency. Our numerical experiments describe the impact of outsourcing on the customer's experience in terms of waiting time and mistreatment. The experiments also describe how contract inefficiency leads the client to outsource components of, or the entire, two-level system.

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Appendix A: Accuracy of The Approximation

We use simulation to test the accuracy of the M/M/N-QED approximation described in Section 4. In our simulation we assume that arrivals to the gatekeeper are Poisson and that all diagnosis and treatment times, given x, are exponential. Therefore, a gatekeeper's total service is the sum of the exponential diagnosis time and the complexity-dependent treatment time, if needed. Let v(x) be the simulated total gatekeeper service time for a problem with complexity x, let κ be an exponential random variable with mean $1/\mu_d$, and let $\tau_g(x)$ be an exponential random variable with mean $t_g(x)$. Therefore,

$$\upsilon(x) \sim \left\{ \begin{array}{c} \kappa \text{ if } x < k^* \\ \\ \kappa + \tau_g(x) \text{ if } x \geq k^* \end{array} \right.$$

Likewise, expert treatment time is distributed as an exponential random variable with mean $t_e(x)$.

Given each set of system parameters, we calculate the treatment threshold and staffing decisions k^* , $n_e^*(k^*, C_w)$ and $n_g^*(k^*, C_w)$ from the M/M/N-QED approximation. We then implement the optimal threshold in the simulation. To find the optimal staffing level in the simulation, we search around n_e^* and n_g^* and identify the staffing levels that generate the lowest total cost in the simulation.

We consider the following parameters in the simulation: $\lambda = 100, 200, \text{ and } 500 \text{ customer requests}$ per minute; $C_e = \$50, \$75, \text{ and } \$100$ per hour; $C_g = 0.5C_e, 0.25C_e, \text{ and } 0.1C_e; C_m = \$0.02, \$0.2,$ and \$1.0 per mistreatment; and $C_w = \$10, \$30, \text{ and } \$90$ per hour. We use treatment time functions $t_g(x) = \bar{t}_g(1 + x\Delta_g)$ and $t_e(x) = \bar{t}_e(1 + x\Delta_e)$. We consider the following parameters for the service times: $\mu_d = 2$ per minute; $\bar{t}_g = 0.5, 0.83, \text{ and } 1.5 \text{ minutes}; \bar{t}_e = 0.9\bar{t}_g, 0.75\bar{t}_g, \text{ and } 0.5\bar{t}_g \text{ minutes};$ $\Delta_e = 0.1, 0.3, \text{ and } 0.5; \text{ and } \Delta_g = 0.1, 0.3, \text{ and } 0.5.$ Finally, we use a linear treatment function, f(x) = 1 - bx, with b = 1. To ensure that experiments generated a full range of values for k^* (there were relatively few experiments with $k^* > 0.9$ with the parameters. This generated 15,743 two-level systems that satisfy the convexity constraints of Lemma 2.

For each set of parameters we measure the approximation's accuracy in terms of the total cost. As a measure of accuracy, we use the absolute value of the difference between the total cost from simulation and the total cost from the M/M/N-QED approximation, expressed as a percentage of the total cost from simulation. Table 1 shows the average and maximum percentages for various groups of experiments. The column category k^* is the optimal threshold, given the parameters. The row category *min load* is the smaller of the gatekeeper and expert loads: *min*

			k^*			
min load	0-0.2	0.2-0.4	0.4-0.6	0.6-0.8	0.8-1	total
0-50	0.2 / 0.9	$0.2 \ / \ 0.9$	0.2 / 1.0	0.6 / 2.2	1.8 / 6.0	0.7 / 6.0
50-75	0.2 / 0.9	$0.2 \ / \ 0.8$	$0.3 \ / \ 1.2$	$0.9 \ / \ 2.8$	1.7 / 4.3	0.5 / 4.3
75-100	0.2 / 0.8	$0.2 \ / \ 0.9$	$0.3 \ / \ 1.1$	$0.9 \ / \ 2.5$	1.8 / 3.7	0.6 / 3.7
100-150	0.2 / 0.8	$0.2 \ / \ 0.6$	$0.4 \ / \ 1.4$	$0.9 \ / \ 2.4$	1.4 / 3.2	0.5 / 3.2
150-225	0.2 / 0.7	$0.2 \ / \ 0.7$	$0.5 \ / \ 1.1$	$0.9 \ / \ 2.2$	1.3 / 2.5	0.5 / 2.5
>225	$0.3 \ / \ 0.7$	$0.3 \ / \ 0.8$	$0.5 \ / \ 1.1$	$0.9 \ / \ 1.7$	1.2 / 2.1	0.5 / 2.1
total	$0.2 \ / \ 0.9$	$0.2 \ / \ 0.9$	$0.4 \ / \ 1.4$	$0.8 \ / \ 2.8$	$1.6 \ / \ 6.0$	$0.6 \ / \ 6.0$

Table 1: Total cost error (Average/Max error) in %.

 $load = \min \left[\lambda/\mu_g(k^*), (1 - F(k^*))\lambda/\mu_e(k^*) \right]$. For example, for the 929 experiments with $0.2 \leq k^* < 0.4$ and a minimum load from 50 – 75, the average approximation error for the total cost was 0.2% and the maximum was 0.8%. The number of experiments associated with each entry in the table varies from approximately 150 to 1000, and the experiments are roughly evenly distributed over the entire ranges of minimum loads and k^* . Overall, the average cost error was 0.6%, with a maximum of 6%. We see that the accuracy of the approximation depends both upon the size of the load placed on each resource pool, as well as the value of k^* . Because the approximations are based on limiting behavior as the system size increases, it is no surprise the performance is best for large loads: for systems with minimum loads above 50, the average error is 0.5% and the maximum error is 4.3%.

We believe that the growth in approximation error as k^* rises is due to the gatekeeper servicetime distribution. As k^* grows, a larger proportion of the simulated gatekeeper service times are the sums of two exponentials, which can be poorly approximated by a single exponential in small systems. In addition, the relationship between problem complexity and treatment time adds to the approximation inaccuracy: when $k^* = 0$, gatekeeper treatment times follow a single exponential distribution. As k^* rises, gatekeeper treatment times become a mix of exponential distributions with a wider range of mean values.

Appendix B: Proofs

Lemma 1 If $C_w > 0$, then the optimal excess capacity β^* satisfies $d(\alpha(\beta))/d\beta|_{\beta=\beta^*} = -C_n/C_w$ and is strictly increasing in C_w .

Proof. By substituting N and W into Equation (2), we write the total cost in terms of the standardized excess capacity β , $\hat{C}(\beta) = C_n \left(\rho + \beta \sqrt{\rho}\right) + C_w \sqrt{\rho} \alpha(\beta)$. We then find that $d\hat{C}(\beta)/d\beta = C_n \sqrt{\rho} + C_w \sqrt{\rho} (d\alpha(\beta)/d\beta)$ and $d^2 \hat{C}(\beta)/d\beta^2 = C_w \sqrt{\rho} (d^2 \alpha(\beta)/d\beta^2)$. Because $d(\alpha(\beta))/d\beta < 0$ and $d^2(\alpha(\beta))/d\beta^2 > 0$ (Borst, Mandelbaum and Reiman, 2004), $\hat{C}(\beta)$ is decreasing and convex in β . As a result, when $C_w > 0$, a solution satisfying $\partial \hat{C}(\beta)/\partial \beta = 0$ exists, i.e., the optimal standardized excess capacity β^* , and it satisfies $d(\alpha(\beta))/d\beta |_{\beta=\beta^*} = -C_n/C_w$.

Now let $h(\beta, C_w) = d(\alpha(\beta))/d\beta + C_n/C_w$. By the definition of the optimal standardized excess capacity, $h(\beta^*, C_w) = 0$. We calculate the relationship between β^* and C_w using implicit differentiation:

$$\frac{d\beta^*}{dC_w} = -\frac{\partial h(\beta, C_w)/\partial C_w}{\partial h(\beta, C_w)/\partial \beta} \left|_{\beta=\beta^*}\right|_{\beta=\beta^*}$$

The numerator $\partial h(\beta, C_w)/\partial C_w = -1/C_w^2$, while the denominator is, $\partial h(\beta, C_w)/\partial \beta |_{\beta=\beta^*} = \alpha''(\beta) |_{\beta=\beta^*}$. Therefore, $d\beta^*/dC_w = 1/[C_w^2\alpha''(\beta^*)] > 0$, in which the inequality follows from $C_w > 0$ and the fact that $\alpha(\beta)$ is strictly convex in β .

Lemma 2 $\pi_c(k)$ is a strictly convex function in k if (1) $\lambda > \tilde{\lambda}_c$ and (2) $\partial^2 T_e(k)/\partial k^2 > 0$ for all k, in which $\tilde{\lambda}_c = t_g^4 \mu_g^3 C_g^2 \eta_g^2(C_w)/16H_c^2$, and $H_c = -C_m f'(k^*) - C_e V(k^*) - C_e \eta_e(C_w) t_e^2 f^2(k^*)/4T_e^{3/2}$. Proof. The client's cost function can be decomposed into three parts, $\pi_c(k) = \hat{C}_m(k) + \hat{C}_e(k) + \hat{C}_g(k)$, in which $\hat{C}_m(k) = C_m \lambda(k - F(k)), \hat{C}_e(k) = C_e \rho_e (1 + 2\Theta_e(k, C_w))$, and $\hat{C}_g(k) = C_g \rho_g (1 + 2\Theta_g(k, C_w))$. The second derivatives of these three functions are,

$$\frac{\partial^2 \hat{C}_m(k)}{\partial k^2} = -C_m f'(k) \lambda \ge 0, \tag{A1}$$

$$\frac{\partial^2 \widehat{C}_e(k)}{\partial k^2} = -C_e \lambda \left(1 + \Theta_e(k, C_w)\right) V(k) - C_e \lambda \Theta_e(k, C_w) \frac{t_e^2 f^2(k)}{2T_e},\tag{A2}$$

$$\frac{\partial^2 \widehat{C}_g(k)}{\partial k^2} = C_g \lambda t'_g + \frac{C_g \lambda \eta_g(C_w) t'_g}{2\sqrt{\lambda/\mu_g}} - \frac{C_g \lambda t^2_g \eta_g(C_w)}{4\sqrt{\lambda/\mu_g}^3}.$$
 (A3)

Recall the definition of $V(k) = -\partial^2 T_e(k)/\partial k^2$. Condition 2 implies that V(k) < 0. This inequality, combined with Condition 1, $\lambda > \tilde{\lambda}_c$, ensures that the sum of Equations (A1), (A2), and (A3) is positive. Therefore, the client's cost function is strictly convex.

Lemma 3 k^* is strictly decreasing with respect to C_w if (1) $\lambda > \tilde{\lambda}_c$ and (2) $t_g > \tilde{\alpha}t_e$, in which $\tilde{\alpha} = (f(k^*)/\sqrt{\mu_g T_e})(\alpha(\beta_e^*(C_w))/\alpha(\beta_g^*(C_w))).$

Proof. We abbreviate $\Theta_e(k^*, C_w)$ as Θ_e and $\Theta_g(k^*, C_w)$ as Θ_g . From Equation (5), $r^*(C_m + C_e t_e (1 + \Theta_e)) = C_m + C_g t_g (1 + \Theta_g)$. Taking the derivative with respect to C_w ,

$$\frac{\partial k^*}{\partial C_w} A_c = t_g \frac{\alpha(\beta_g^*(C_w))}{2\sqrt{\lambda/\mu_g}} - f(k^*) t_e \frac{\alpha(\beta_e^*(C_w))}{2\sqrt{\lambda T_e}},$$

in which $-A_c\lambda$ is the second derivative of $\pi_c(k)$, and hence $A_c < 0$ if Condition 1 is satisfied. Moreover, Condition 2 implies that the right-hand side of the equation is positive. As a result, $\partial k^*/\partial C_w$ is negative and k^* is strictly decreasing with respect to C_w .

Proposition 1 A contract with system-time-penalty + pay-per-service components coordinates the system if the client offers the contract $(Q^e, P^e) = (C_w, C_e \rho_e [1 + 2\Theta_e(k^*, C_w)] / \lambda_e + C_w T_e(k^*) / (1 - F(k^*))).$

Proof. The contract implies that the client pays the transfer payment $\lambda_e \left[P^e - Q^e \left(T_e(k)/(1 - F(k)) + W_e\right)\right]$ to the vendor and the vendor staffs the expert subsystem with a unit waiting cost Q^e . By applying the square root rule to both subsystems, the client's cost can be formulated as a function of k, Q^e , and P^e ,

$$\begin{aligned} \pi^e_c(k,Q^e,P^e) &= C_m \lambda(k-F(k)) + C_g \rho_g \left[1 + 2\Theta_g(k,C_w)\right] \\ &+ (1-F(k))\lambda \left(P^e - Q^e T_e(k)/(1-F(k))\right) + (C_w - Q^e) \,\alpha(\beta^*_e(Q^e)) \sqrt{\rho_e}. \end{aligned}$$

The value of Q^e in this contract ensures that the vendor staffs the expert subsystem at the optimal level if the client sets the threshold to k^* . It also ensures that the client does not bear the waiting cost at the vendor, e.g., $(C_w - Q^e) \alpha(\beta_e^*(Q^e)) \sqrt{\rho_e} = 0$ in the client's cost function. By substituting (Q^e, P^e) into the client's cost function,

$$\pi_{c}^{e}(k) = C_{m}\lambda(k - F(k)) + C_{g}\rho_{g}\left[1 + 2\Theta_{g}(k, C_{w})\right] + C_{e}\rho_{e}\left[1 + 2\Theta_{e}(k, C_{w})\right].$$

Because the lowest cost the client can achieve is $\pi_c(k^*)$, the client chooses the optimal threshold k^* and the optimal staffing level for the gatekeeper subsystem $n_g^*(k^*, C_w)$.

Lemma 4 $\pi_v^g(k)$ is a strictly concave function in k if $\lambda > \tilde{\lambda}_g$, in which $\tilde{\lambda}_g = t_g^4 \mu_g^3 C_g^2 \eta_g^2 (Q^g) / 16 H_g^2$ and $H_g = -f'(k) R^g + Q^g t'_g + C_g \lambda t'_g$.

Proof. The second derivative of the profit function $\pi_v^g(k)$ is

$$\frac{\partial^2 \pi_v^g(k)}{\partial k^2} = \lambda \left[f'(k) R^g - Q^g t'_g - C_g \lambda t'_g \right] + \frac{C_g \eta_g(Q^g) \sqrt{\mu_g}}{4} \left[t_g^2 \mu_g - 2t'_g \right] \sqrt{\lambda}$$

 $\lambda > \tilde{\lambda}_g$, implies that the right-hand side is positive, and hence $\pi_v^g(k)$ is a strictly concave.

Proposition 2 A contract with system-time-penalty + pay-per-service + pay-per-solve components coordinates the system if the client offers $(Q^g, P^g, R^g) = (C_w, C_g \rho_g [1 + 2\Theta_g(k^*, C_w)] / \lambda - F(k^*) R^g + C_w (1/\mu_d + T_g), t_g [C_w + C_g (1 + \Theta_g(k^*, C_w))] / r^*).$

Proof. The contract implies that the client pays the transfer payment $\lambda [P^g + R^g F(k) - Q^g(1/\mu_d + T_g + W_g)]$, and the vendor staffs the gatekeeper subsystem, given the waiting cost Q^g . Because the threshold k^g is determined by solving $\partial \pi_v^g(k)/\partial k = 0$ and the expert's staffing is determined by the client using the square root staffing rule, the client's cost is a function of the contract terms,

$$\begin{aligned} \pi_c^g(Q^g, P^g, R^g) &= C_m \lambda(k^g - F(k^g)) + (P^g + F(k^g)R^g) \lambda - Q^g \lambda \left(1/\mu_d + k^g T_g\right) \\ &+ (C_w - Q^g) \,\alpha(\beta_g^*(Q^g)) \sqrt{\rho_g(k^g)} + C_e \rho_e(k^g) \left[1 + 2\Theta_e(k^g, C_w)\right]. \end{aligned}$$

First, the value of Q^g ensures that the threshold is set to the optimal level. Furthermore, because $Q^g = C_w$, the waiting cost that the client bears, $(C_w - Q^g) \alpha(\beta_g^*(Q^g)) \sqrt{\rho_g}$, becomes 0. Specifically, by using the system-time penalty, the client shifts the waiting cost to the vendor and force him to staff optimally. Second, for $k^g = k^*$, we require $r^g = r^*$. Specifically, $R^g = t_g [C_w + C_g (1 + \Theta_g(k^*, C_w))] / r^*$, in which Q^g has been replaced by C_w . Because $k^g = k^*$, the expert's staffing level for the client is optimal as well. As a result, this contract coordinates the system. The contract also needs to satisfy the vendor's reservation level, i.e., $\pi_v^g(k^*) = 0$. Thus, to ensure that the client extracts all the vendor's profit while the vendor is still willing to accept the contract, we use

$$P^{g} = C_{g} \rho_{g} \left[1 + 2\Theta_{g}(k^{*}, C_{w}) \right] / \lambda - F(k^{*}) R^{g} + C_{w} \left(1/\mu_{d} + T_{g} \right).$$

Lemma 5 $\pi_v^b(k)$ is a strictly concave function in k if (1) $\lambda > \tilde{\lambda}_b$ and (2) $\partial^2 T_e(k)/\partial k^2 > 0$ for all k, in which $\tilde{\lambda}_b = t_g^4 \mu_g^3 C_g^2 \eta_g^2 (Q^b)/16H_b^2$ and $H_b = -(Q^b + C_e) V(Q^b) + Q^b t'_g - C_e \eta_e (Q^b) t_e^2 f^2(k)/4T_e^{3/2}$. Proof. The proof of this lemma is similar to the proof of Lemma 2. We first decompose the profit function $\pi_v^b(k)$ into three parts: $\hat{R}^b(k) - \hat{C}_g^b(k) - \hat{C}_e^b(k)$, in which $\hat{R}^b(k) = P^b \lambda - Q^b \lambda [1/\mu_d + T_e + T_g]$, $\hat{C}_g^b(k) = C_g \rho_g (1 + 2\Theta_g(k, Q^b))$, and $\hat{C}_e^b(k) = C_e \rho_e (1 + 2\Theta_e(k, Q^b))$. Similar to the proof in Lemma 2, Equation (A1) is replaced by $Q^b (V(k) + t'_g)$ and the waiting cost C_w in Equation (A2) and (A3) is replaced by Q^b . As a result, if the conditions are satisfied, $\pi_v^b(k)$ is strictly concave. **Lemma** 6 If (1) $\lambda > \tilde{\lambda}_b$ and (2) $\partial^2 T_e(k) / \partial k^2 > 0$ for all k, and (3) $t_g \ge \max(1, \tilde{\alpha}) t_e$ for $0 \le k \le 1$, then k^b is strictly decreasing with Q^b .

Proof. We abbreviate $\Theta_e(k^b, Q^b)$ as Θ_e and $\Theta_g(k^b, Q^b)$ as Θ_g . By taking the derivative of Equation (7) we find that $\partial k^b / \partial Q^b$ satisfies,

$$A_v^b \frac{\partial k^b}{\partial Q^b} = t_g - t_e f(k^b) + \frac{t_g \alpha \left(\beta_g^*(Q^b)\right)}{2\sqrt{\lambda/\mu_g}} - \frac{t_e f(k^b) \alpha \left(\beta_e^*(Q^b)\right)}{2\sqrt{\lambda T_e}},\tag{A4}$$

in which $A_v^b \lambda$ is the second derivative of $\pi_v^b(k)$. Under Conditions 1 and 2, we know that $\pi_v^b(k)$ is concave, and hence $A_v^b < 0$. Condition 3 guarantees that $t_g - t_e f(k^b) \ge 0$ and that the difference between the last two terms in the right-hand side of Equation (A4) is positive. Because $A_v^b < 0$ and the right-hand side of Equation (A4) is positive, $\partial k^b / \partial Q^b < 0$.

Proposition 3 A contract with system-time-penalty + pay-per-service components, (Q^b, P^b) , coordinates the system if and only if

$$Q^{b} = C_{w} = \left[f(k^{*})C_{e}t_{e}\left(1 + \Theta_{e}(k^{*}, C_{w})\right) - C_{g}t_{g}\left(1 + \Theta_{g}(k^{*}, C_{w})\right)\right] / \left[t_{g} - f(k^{*})t_{e}\right].$$

Proof. Let $k^b(Q^b)$ be the vendor's optimal threshold, given Q^b , and let $n_g^*(k, Q^b)$ and $n_e^*(k, Q^b)$ be the vendor's optimal gatekeeper's and expert's staffing levels, given threshold k and penalty Q^b . We want to show that $k^b(Q^b) = k^*$, $n_g^*(k^b(Q^b), Q^b) = n_g^*(k^*, C_w)$, and $n_e^*(k^b(Q^b), Q^b) = n_e^*(k^*, C_w)$ if and only if Q^b and the parameters of the model satisfy the conditions above.

First, note that k^* is unique due to the strict convexity of the objective function (see Lemma 2). Given the workflow implied by k^* , both $n_g^*(k^*, C_w)$, and $n_e^*(k^*, C_w)$ are unique (Borst, Mandelbaum and Reiman, 2004).

We now show that the conditions on Q^b and the parameters are sufficient conditions. If $Q^b = [r^*C_et_e(1 + \Theta_e(k^*, C_w)) - C_gt_g(1 + \Theta_g(k^*, C_w))] / [t_g - r^*t_e]$, then $r^b = r^*$. Because f is strictly decreasing, this implies that $k^b(Q^b) = f^{-1}(r^b) = f^{-1}(r^*) = k^*$. Given the workflow implied by k^* , and if $Q^b = C_w$, the vendor applies the square root staffing rule to the gatekeeper and expert subsystems so that for $i \in \{g, e\}$, $n_i^*(k^b(Q^b), Q^b) = n_i^*(k^*, C_w)$.

We now show that the conditions are necessary. First note that because f is strictly decreasing, if k^* is optimal for the vendor then $r^b = r^*$, and therefore

$$Q^{b} = [r^{*}C_{e}t_{e}\left(1 + \Theta_{e}(k^{*}, Q^{b})\right) - C_{g}t_{g}\left(1 + \Theta_{g}(k^{*}, Q^{b})\right)]/[t_{g} - r^{*}t_{e}].$$

Finally we show that if $n_i^*(k^*, Q^b) = n_i^*(k^*, C_w)$, $i \in \{g, e\}$, then $Q^b = C_w$. By the vendor's square root staffing rule,

$$n_i^*(k^*,Q^b) = \rho_i(k^*) + \beta_i^*(Q^b) \sqrt{\rho_i(k^*)}.$$

Recall that the optimal centralized staffing solution is,

$$n_i^*(k^*, C_w) = \rho_i(k^*) + \beta_i^*(C_w) \sqrt{\rho_i(k^*)}.$$

Therefore $\beta_i^*(Q^b) = \beta_i^*(C_w)$. Because β_i^* is strictly increasing in its argument (Lemma 1), $Q^b = C_w$. Thus we can replace Q^b and obtain the condition,

$$Q^{b} = C_{w} = [f(k^{*})C_{e}t_{e} (1 + \Theta_{e}(k^{*}, C_{w})) - C_{g}t_{g} (1 + \Theta_{g}(k^{*}, C_{w}))]/[t_{g} - f(k^{*})t_{e}].$$

Corollary 2 The mistreatment cost C_m that satisfies the coordination condition increases with the waiting cost C_w if (1) $\lambda > \tilde{\lambda}_c$, (2) $t_g \ge \max(1, \tilde{\alpha})t_e$ for $0 \le k \le 1$, and (3) $t'_g \le (t_g - t_e)(-f'(k^*)) / (1 - f(k^*)) + t'_e f(k^*)$.

Proof. We abbreviate $\Theta_e(k^*, C_w)$ as Θ_e and $\Theta_g(k^*, C_w)$ as Θ_g . After some algebra, $C_m(1 - f(k^*)) = C_w(t_g - t_e f(k^*))$. Taking the derivative with respect to C_w ,

$$\frac{dC_m}{dC_w}\left(1 - f(k^*)\right) = A^* \frac{\partial k^*}{\partial C_w} + \left(t_g - t_e f(k^*)\right),$$

in which $A^* = [C_w t_e - C_m] (-f'(k^*)) + C_w (t'_g - t'_e f(k^*))$. From Lemma 3, we know that $\partial k^* / \partial C_w < 0$ if Conditions 1 and 2 are satisfied. Also from Condition 2, $t_g - t_e f(k^*) \ge 0$, because $f(k) \le 1$, for $0 \le k \le 1$.

After replacing C_m with $C_w \left(t_g - t_e f(k^*) \right) / (1 - f(k^*))$,

$$A^* = \frac{C_w}{1 - f(k^*)} \left[(t_e - t_g) \left(-f'(k^*) \right) + \left(t'_g - t'_e f(k^*) \right) \left(1 - f(k^*) \right) \right]$$

From Condition 3, $A^* \leq 0$. Therefore, given the four conditions, $dC_m/dC_w \geq 0$.

Proposition 4 Assume that $\lambda > \widetilde{\lambda}_*^b$. The client offers a contract $(Q^b, P^b) = (Q^b_*, P^b_*)$, in which

$$Q_*^b = \left[C_e t_e \left[1 + \Theta_e(k_*^b, Q_*^b) \right] r_*^b - C_g t_g \left[1 + \Theta_g(k_*^b, Q_*^b) \right] \right] / [t_g - r_*^b t_e], \text{ and}$$
$$P_*^b = Q_*^b t(k_*^b) - \left[C_e \rho_e \left[1 + 2\Theta_e(k_*^b, Q_*^b) \right] + C_g \rho_g \left[1 + 2\Theta_g(k_*^b, Q_*^b) \right] \right] / \lambda,$$

and the vendor sets the threshold at $k^b = k^b_* = f^{-1}(r^b_*)$, in which $r^b_* = (C_m + C_g t_g (1 + \Psi_g(k^b_*))) / C_m + C_e t_e (1 + \Psi_e(k^b_*))$, $\Psi_i(k) = \tilde{\eta}_i(Q^b) / [2\sqrt{\rho_i}]$ and $\tilde{\eta}_i(Q^b) = \beta^*_i(Q^b) + C_w \alpha(\beta^*_i(Q^b)) / C_i$, for $i \in \{e, g\}$, $\tilde{\lambda}^b_* = t^4_g \mu^3_g C^2_g \tilde{\eta}^2_g (Q^b_*) / 16 (H^b_*)^2$, and $H^b_* = -C_m f'(k^b_*) - C_e V(Q^b_*) - C_e \tilde{\eta}^2_e (Q^b_*) t^2_e f^2(k^b_*) / 4T^{3/2}_e$.

Proof. This proof has three parts. First we will prove that Q^b and k^b have a one-to-one mapping. Next, the cost function becomes an implicit function of k^b , i.e., $\pi^b_c(Q^b(k^b))$, and if it is convex with k^b , then we can find the optimal threshold k^b_* for the client. Finally, we find the optimal contract (Q^b_*, P^b_*) in which P^b_* forces the vendor to accept the contract while earning zero profit, and Q^b_* forces the vendor to set the threshold at k^b_* because of the one-to-one mapping. In the following, we abbreviate $\beta^*_e(Q^b)$ as β^*_e , $\beta^*_g(Q^b)$ as β^*_g , $\Theta_e(k^b, Q^b)$ as Θ_e and $\Theta_g(k^b, Q^b)$ as Θ_g .

First, assume that Q^b and k^b do not have a one-to-one mapping. Therefore there exist Q^{b_1} and Q^{b_2} ($Q^{b_1} < Q^{b_2}$) that generate the thresholds k^{b_1} and k^{b_2} so that $k^{b_1} = k^{b_2} = \tilde{k}^b$. For any Q^b , such that $Q^{b_1} < Q^b < Q^{b_2}$, Lemma 6 implies that the threshold k^b has to satisfy $k^{b_2} < k^b < k^{b_1}$. But because $k^{b_1} = k^{b_2} = \tilde{k}^b$, there is a contradiction, and Q^b and k^b have a one-to-one mapping

Next, We calculate the first and the second derivatives of $\pi_c^b(Q^b(k^b))$ with respect to k^b :

$$\begin{aligned} \frac{\partial \pi_c^b(Q^b(k^b))}{\partial k^b} &= C_m \lambda (1 - f(k^b)) + C_g t_g \left(1 + \Psi_g(k^b) \right) \lambda - C_e t_e f(k^b) \left(1 + \Psi_e(k^b) \right) \lambda, \text{ and} \\ \frac{\partial^2 \pi_c^b(Q^b(k^b))}{\partial \left(k^b\right)^2} &= -C_m \lambda f'(k^b) + C_g t'_g \left(1 + \Psi_g(k^b) \right) \lambda - C_e V(k^b) \left(1 + \Psi_e(k^b) \right) \lambda \\ - \Psi_g \frac{C_g t_g^2 \mu_g}{2} \lambda - C_e \Psi_e \frac{t_e^2 f^2(k^b)}{2T_e} \lambda, \end{aligned}$$

in which $\Psi_i(k) = \left[\beta_i^*(Q^b) + (C_w/C_i)\alpha(\beta_i^*(Q^b))\right]/[2\sqrt{\rho_i}]$. As in Lemma 2, we know that if $\lambda > \widetilde{\lambda}_*^b$, then the client's cost function $\pi_c^b(Q^b(k^b))$ is strictly convex.

Finally, the optimal k^b that the client prefers can be obtained by setting the first derivative of $\pi^b_c(Q^b(k^b))$ with respect to k^b to zero. As a result, $k^b = k^b_*$, in which $k^b_* = f^{-1}(r^b_*)$, and

$$r_*^b = \frac{C_m + C_g t_g \left(1 + \Psi_g(k_*^b)\right)}{C_m + C_e t_e \left(1 + \Psi_e(k_*^b)\right)}.$$

Therefore, the client offers a contract $(Q^b, P^b) = (Q^b_*, P^b_*)$, in which

$$Q_*^b = \left[C_e t_e \left[1 + \Theta_e(k_*^b, Q_*^b) \right] r_*^b - C_g t_g \left[1 + \Theta_g(k_*^b, Q_*^b) \right] \right] / [t_g - r_*^b t_e], \text{ and}$$
$$P_*^b = Q_*^b t(k_*^b) - \left[C_e \rho_e \left[1 + 2\Theta_e(k_*^b, Q_*^b) \right] + C_g \rho_g \left[1 + 2\Theta_g(k_*^b, Q_*^b) \right] \right] / \lambda.$$

Proposition 5 Given the conditions of Lemma 2 and Proposition 4, Q^b_* increases with C_w and k^b_* decreases with C_w .

Proof. The optimal system-time penalty Q^b_* can be obtained by setting the first derivative of the cost function $\pi^b_c(Q^b)$ equal to zero, given that the unit waiting cost is C_w : $\partial \pi^b_c(Q^b) / \partial Q^b \Big|_{Q^b = Q^b_*} = 0$. By the implicit theorem,

$$\frac{dQ_*^b}{dC_w} = -\frac{\partial^2 \pi_c^b(Q^b)/\partial Q^b \partial C_w \left|_{Q^b = Q_*^b}\right|}{\partial^2 \pi_c^b(Q^b)/\partial \left(Q^b\right)^2 \left|_{Q^b = Q_*^b}\right|}$$

Because $\pi_c^b(Q^b)$ is convex in Q^b , the sign of dQ_*^b/dC_w is the sign of $-\partial^2 \pi_c^b(Q^b)/\partial Q^b \partial C_w \Big|_{Q^b = Q_*^b}$,

$$\begin{split} -\frac{\partial^2 \pi_c^c(Q^b)}{\partial Q^b \partial C_w} \left|_{Q^b = Q^b_*} \right| &= \frac{C_g}{Q^b_*} \frac{\partial \beta_g^*(Q^b)}{\partial Q^b} \left|_{Q^b = Q^b_*} \sqrt{\rho_g(k^b_*)} + \frac{C_e}{Q^b_*} \frac{\partial \beta_e^*(Q^b)}{\partial Q^b} \left|_{Q^b = Q^b_*} \sqrt{\rho_e(k^b_*)} \right. \\ &\left. -\frac{\alpha \left(\beta_g^*(Q^b_*)\right)}{2\sqrt{\rho_g(k^b_*)}} \left(\lambda t_g\right) \frac{\partial k^b}{\partial Q^b} \left|_{Q^b = Q^b_*} + \frac{\alpha \left(\beta_e^*(Q^b_*)\right)}{2\sqrt{\rho_e(k^b_*)}} \left(\lambda t_e f(k^b_*)\right) \frac{\partial k^b}{\partial Q^b} \left|_{Q^b = Q^b_*} \right. \end{split}$$

By using Lemma 1 and Lemma 6, we see that $-\partial^2 \pi^b_c(Q^b)/\partial Q^b \partial C_w \Big|_{Q^b = Q^b_*} > 0$ and thus $dQ^b_*/dC_w > 0$. The second part of this proposition can be proved by using the chain rule and Lemma 6.

Proposition 6 Given the conditions of Lemma 2 and Proposition 4, Q_*^b increases with C_m and k_*^b decreases with C_m .

Proof. The proof is similar to Proposition 5, except that $-\partial^2 \pi_c^b(Q^b)/\partial Q^b \partial C_m \Big|_{Q^b = Q_*^b}$ is

$$-\frac{\partial^2 \pi_c^b(Q^b)}{\partial Q^b \partial C_m} \Big|_{Q^b = Q^b_*} = -\frac{\partial k^b}{\partial Q^b} \left(1 - f(k^b)\right) > 0.$$

As a result, $dQ_*^b/dC_m > 0$. Furthermore, because $\partial k^b/\partial Q^b < 0$ (from Lemma 6), we also have $\partial k_*^b/\partial C_m < 0$ by the chain rule.

Lemma 7 For a given Q, the client only offers contract $(Q, \min(P^1(Q), P^b(Q)))$ to the vendor.

Proof. To simplify the notation, we suppress the dependence of $P^1(Q)$ and $P^b(Q)$ on Q in the proof. First, a contract (Q, P) in which $P < \min(P^1, P^b)$ is not feasible because it violates the vendor's IR constraints regardless of his process choice. Next, for a given Q, the staffing and treatment threshold decisions (for a two-level process) are known; the value of P will not affect the vendor's decision variables. Therefore, for a given Q, the client will reduce P but still keep it feasible for the vendor, i.e., $P \in [\min(P^1, P^b), \max(P^1, P^b)]$.

Next, we can divide the contract space into three regimes: (1) $P^1 < P^b$, (2) $P^1 > P^b$, or (3) $P^1 = P^b$. In the first regime, the vendor will choose the one-level process over two. If the vendor chooses a two-level process, he earns zero profit if $P = P^b$, or earns a negative profit if $P < P^b$. However, if he deviates to a one-level process, he earns a positive profit if $P^1 < P \le P^b$ and earns a zero profit if $P = P^1$. Because the client anticipates the vendor's choice, the client will not offer any extra pay-per-service payment to the vendor. Therefore, she will only offer $P = P^1$ in this case. Similarly, in the second regime, the vendor will chooses a two-level process, and hence the client only offers $P = P^b$ to the vendor. Finally, in the third regime, the only contract the client can offer is $P = P^1 = P^b$. As a result, the client only offers contracts $(Q, \min(P^1, P^b))$.



Figure A.1 The contract space and the corresponding IR constraints when the vendor chooses a one-level or a two-level process, i.e., the lines with $\pi_v^{\ l}$ and $\pi_v^{\ b}$ on the right.

Figure B 1: The contract space and the corresponding IR constraints when the vendor chooses a one-level or a two-level process, i.e., the lines with π_v^1 and π_v^b on the right.

Proposition 7 (A) The client's optimal and incentive compatible contract in system S_b is either (Q_*^b, P_*^b) , if $P_*^b \leq P^1(Q_*^b)$, or is (Q_L, P_L) or (Q_{L+1}, P_{L+1}) , if $P_*^b > P^1(Q_*^b)$. (B) The client's optimal and incentive compatible contract in the one-level system is either (Q^1, P^1) , if $P^1 \leq P^b(Q^1)$, or is (Q_J, P_J) or (Q_{J+1}, P_{J+1}) if $P^1 > P^b(Q^1)$.

Proof.

Throughout the proof we will refer to Figure B1, which represents the contract space, in which we only plot two intersections between the vendor's two rationality constraints for illustration. Note that it is not difficult to prove that $P^1(Q)$ and $P^b(Q)$ are strictly increasing and strictly concave with Q. We divide the contract space into two regimes, (1) $P^b(Q) < P^1(Q)$ (areas I and III in Figure B1) and (2) $P^1(Q) < P^b(Q)$ (area II). When the client offers contracts on the intersections (where $P^1(Q) = P^b(Q)$), the vendor is indifferent between a one-level and a two-level system.

First we find the client's optimal incentive-compatible contract for S_b . If the optimal contract with process monitoring, (Q_*^b, P_*^b) , is in regime 1, or on one of the intersections (i.e., $P_*^b \leq P^1(Q_*^b)$), the vendor will conform to the client's choice. However, if (Q_*^b, P_*^b) is in regime 2, the vendor will deviate to a one-level process. As a result, for the vendor to choose a two-level process, she can only offer contracts in areas I or III. Lemma 7 implies that the contracts in regime 1 satisfy $P = P^b(Q)$. Given $P = P^b(Q)$, the client's cost function $\pi^b_c(Q, P^b(Q))$ is equivalent to the cost function $\pi^b_c(Q^b)$. Following the proof of Proposition 4, we know that $\pi^b_c(Q, P^b(Q))$ is strictly convex with Q, and hence the further the contract is away from (Q^b_*, P^b_*) , the higher the client's cost (the line marked as $\pi^b_c(Q, P^b)$ above the contract space in Figure B1). For Q^b_* , we can find the two adjacent intersections such that $Q_L < Q^b_* < Q_{L+1}$. The convexity of $\pi^b_c(Q, P^b(Q))$ implies that for any $Q > Q_{L+1}$, the client's cost is no lower than $\pi^b_c(Q_{L+1}, P_{L+1})$, and for any $Q < Q_L$, the client's cost is no lower than $\pi^b_c(Q_L, P_L)$. Therefore, the client will only need to choose one from the two nearest intersections as the optimal and incentive compatible contract, i.e., (Q_L, P_L) or (Q_{L+1}, P_{L+1}) , depending on which one yields a smaller client's cost.

Now we find the client's optimal incentive-compatible contract for outsourcing a one-level system. If (Q^1, P^1) is in regime 2 or on one of the intersections, then the vendor will conform to the client's choice. If (Q^1, P^1) is in regime 1, then the client will choose one of the contracts in regime 2 that satisfy $P = P^1(Q)$. For the S_b contract we used the convexity of π_c^b to show that the optimal contract is on an intersection. Here we use a weaker monotonicity property. Given $P = P^1(Q)$, after some simple algebra, the client's cost function when the vendor chooses a one-level system is

$$\pi_c^1(Q, P^1(Q)) = C_e \rho_e(0) \left(1 + \left(\beta^*(Q) + \left(C_w/C_e\right) \alpha(\beta^*(Q))\right) / (2\sqrt{\rho_e(0)}) \right).$$

Because the first derivative of $\pi_c^1(Q, P^1(Q))$ is

$$\frac{d\beta^*(Q)}{dQ} \left(1 - \frac{C_w}{Q}\right) \frac{C_e \sqrt{\rho_e(0)}}{2},$$

we know that when $Q < C_w = Q^1$, $\pi_c^1(Q, P^1)$ decreases with Q, while when $Q > C_w = Q^1$, $\pi_c^1(Q, P^1)$ increases with Q, in which Lemma 1 shows that $d\beta^*(Q)/dQ > 0$. Following the same logic as for Q^b , we know that the client will only choose one of the two nearest intersections.